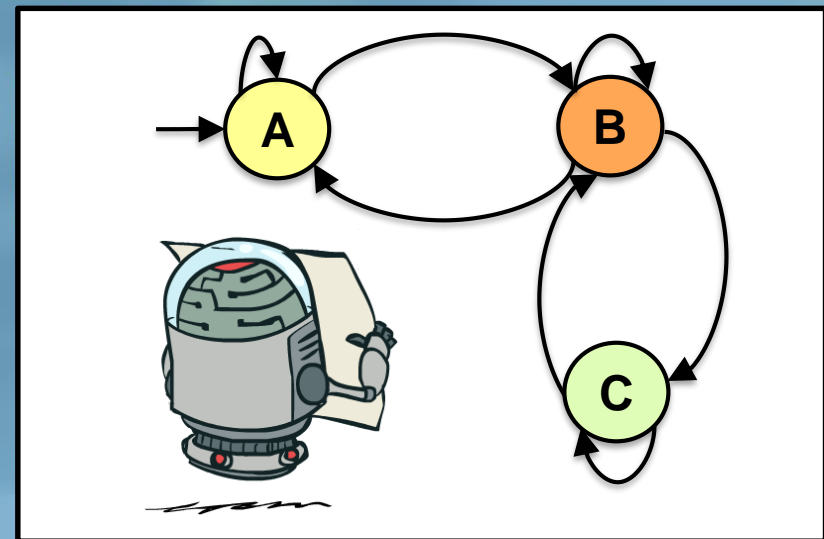
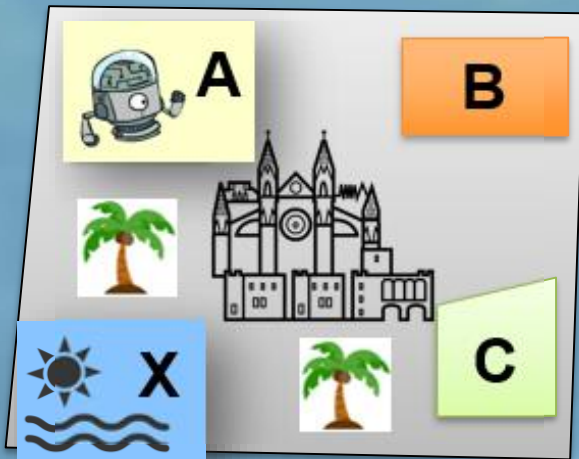


# Temporal Logic + CTL Model Checking



# Part 1 – Properties of CTL / LTL

# Linear Temporal Logic

## LTL

LTL is the set of all **state** formulas, defined below:

State formulas:

- **A**f where f is a **path** formula

Path formulas:

- $p \in AP$
- $\neg f_1, f_1 \vee f_2, f_1 \wedge f_2, \mathbf{X}f_1, \mathbf{G}f_1, \mathbf{F}f_1, f_1 \mathbf{U}f_2, f_1 \mathbf{R}f_2$

where  $f_1$  and  $f_2$  are path formulas

# Computation Tree Logic

## CTL

CTL is the set of all **state** formulas, defined below:

- $p \in AP$
- $\neg g_1, g_1 \vee g_2, g_1 \wedge g_2$
- **AX**  $g_1, \mathbf{AG} g_1, \mathbf{AF} g_1, \mathbf{A} (g_1 \mathbf{U} g_2), \mathbf{A} (g_1 \mathbf{R} g_2)$
- **EX**  $g_1, \mathbf{EG} g_1, \mathbf{EF} g_1, \mathbf{E} (g_1 \mathbf{U} g_2), \mathbf{E} (g_1 \mathbf{R} g_2)$

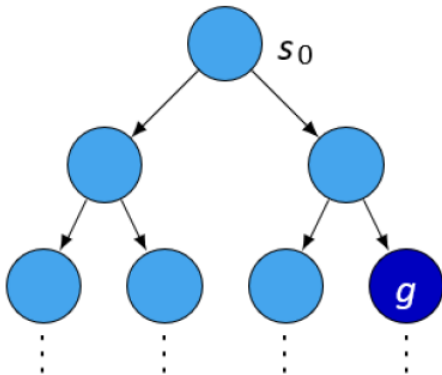
where  $g_1$  and  $g_2$  are state formulas

Note, that all sub-formulas of a CTL formula are **state** formulas

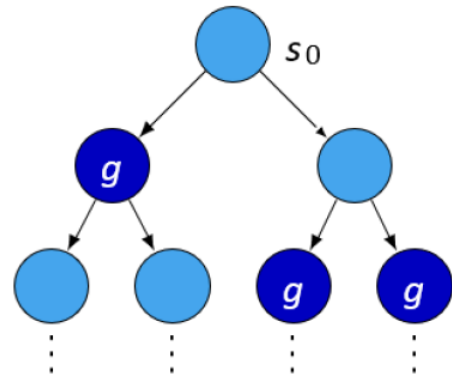
# Illustration of CTL Semantics

EFg

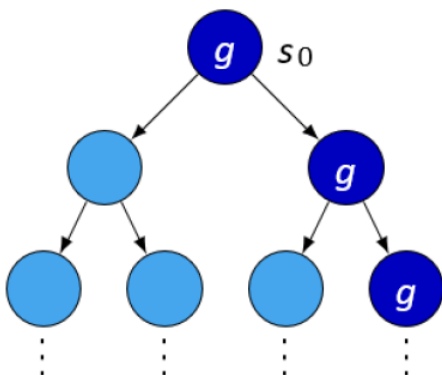
“exists  
reachable  
state such  
that...”



AFg

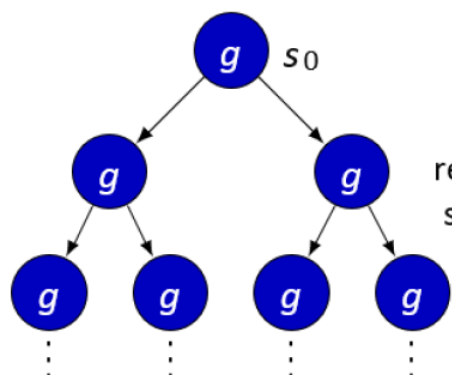


EGg

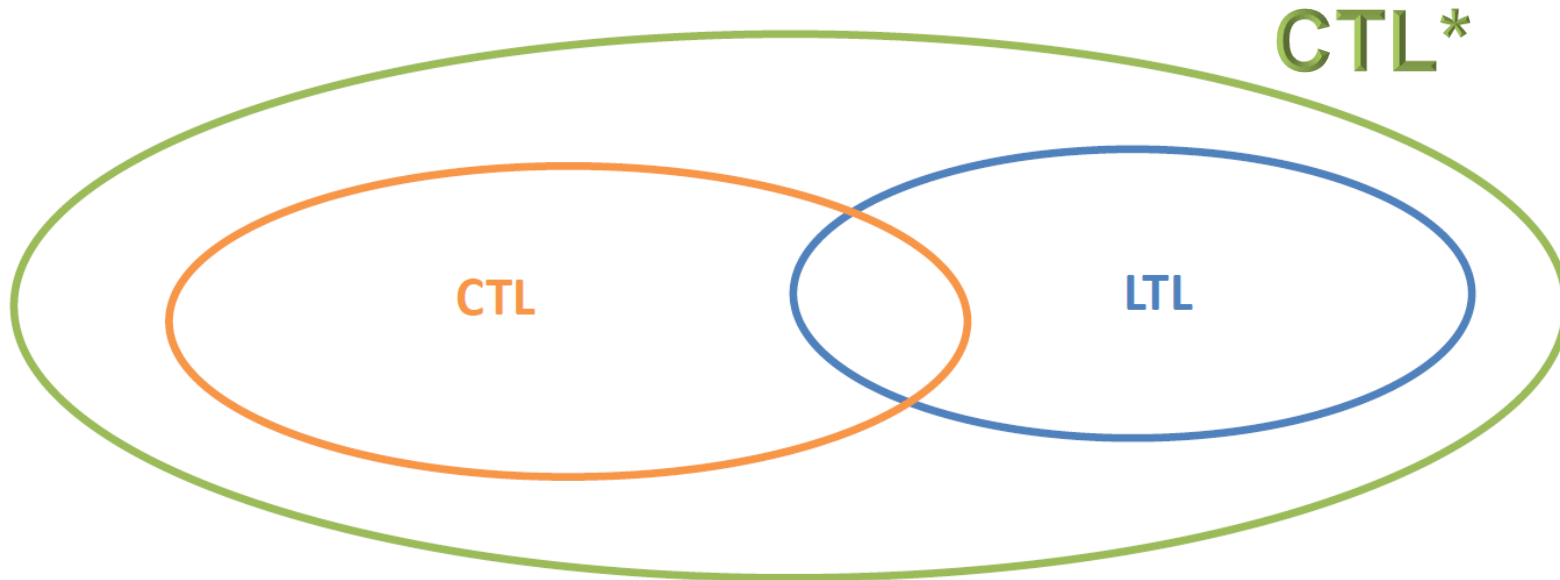


AGg

“all  
reachable  
states...”



# Relationship between LTL and CTL



# LTL vs CTL

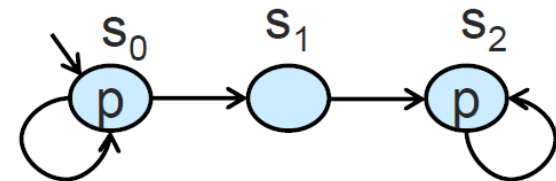


- Exercise:
  - Does the LTL formula  $AFG p$  has an equivalent in CTL?
  - $AFG p$  = “for all paths, eventually  $p$  always holds”
- Solution: No
  - But what about:  $AFAGp$ ?
  - $AFAGp$  = “for all paths, there is a point from which all reachable states satisfy  $p$ ”

# LTL vs CTL



- Exercise:
  - Does the LTL formula  $AFG p$  has an equivalent in CTL?
  - $AFG p$  = “for all paths, eventually  $p$  always holds”
- Solution: No
  - But what about:  $AFAGp$ ?
  - $AFAGp$  = “for all paths, there is a point from which all reachable states satisfy  $p$ ”
    - Consider the given model:
    - Does  $AFGp$  hold?
    - Does  $AFAGp$  hold?

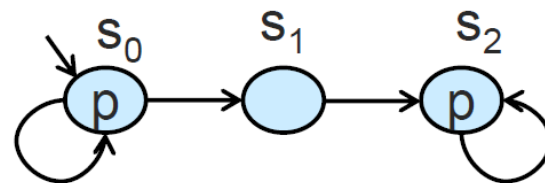




## LTL vs CTL



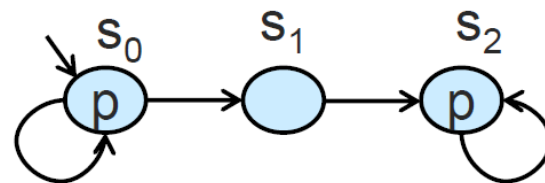
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- Solution: No
  - But what about:  $AFAGp$ ?
  - $AFAGp$  = “for all paths, there is a point from which all reachable states satisfy  $p$ ”
    - Consider the given model:
    - $AFAGp$  holds
      - All paths satisfy  $FGp$
      - $s_0, s_0, s_0, \dots$
      - $s_0, s_0, \dots, s_0, s_1, s_2, s_2, s_2, \dots$



## LTL vs CTL



- Exercise:
  - Does the LTL formula  $AFG p$  has an equivalent in CTL?
  - $AFG p$  = “for all paths, eventually  $p$  always holds”
- Solution: No
  - But what about:  $AFAGp$ ?
  - $AFAGp$  = “for all paths, there is a point from which all reachable states satisfy  $p$ ”
    - Consider the given model:
    - $AFG$  holds
    - $AFAGp$  does not hold
      - $s_0, s_0, s_0, \dots$  does not satisfy  $AFAGp$

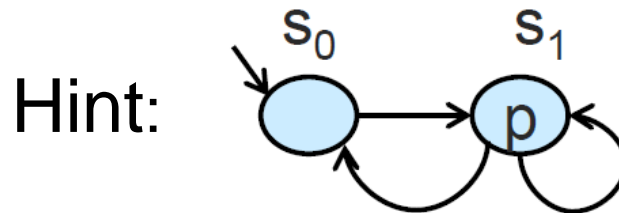


# LTL vs CTL

- Exercise:
  - Does the LTL formula  $AFG p$  has an equivalent in CTL?
  - $AFG p$  = “for all paths, eventually  $p$  always holds”



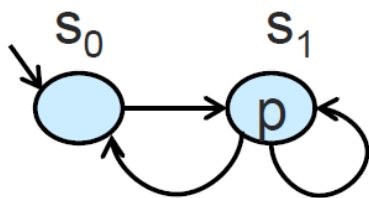
- Solution: No
  - What about  $AFEG p$ ?



## LTL vs CTL



- Exercise:
  - Does the LTL formula ***AFG p*** has an equivalent in CTL?
- Solution: No
  - What about ***AFEG p***?
    - “in every path there is a point from which there is a path where p globally holds”

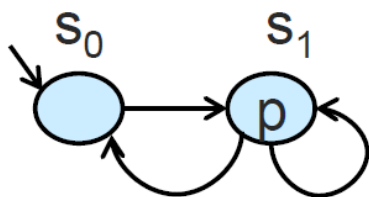


All paths satisfy ***FEGp***  
- since  $s_1$  sat ***EGp***

## LTL vs CTL



- Exercise:
  - Does the LTL formula ***AFG p*** has an equivalent in CTL?
- Solution: No
  - What about ***AFEG p***?
    - “in every path there is a point from which there is a path where p globally holds”



All paths satisfy ***FEGp***

- since  $s_1$  sat ***EGp***

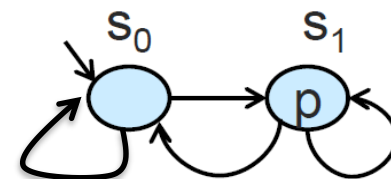
But  $s_0, s_1, s_0, s_1, s_0, s_1, \dots$  does not satisfy ***FGp***

## LTL vs CTL



- Exercise:
  - Does  $AG(EF p)$  has an LTL equivalent?
  - $AG(EF p) =$  “From all reachable states, it is possible to reach a state that satisfies  $p$ ”
- What about  $AGF p =$  “In all paths,  $p$  holds infinitely often”?
  - Does  $AG(EFp)$  hold?
  - Does  $AGFp$  hold?

Hint:

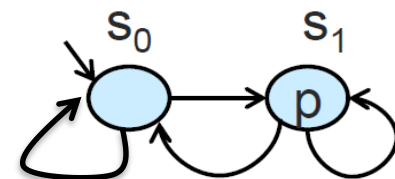


## LTL vs CTL



- Exercise:
  - Does  $AG(EF p)$  has an LTL equivalent?
  - $AG(EF p) =$  “From all reachable states, it is possible to reach a state that satisfies  $p$ ”
- What about  $AGF p =$  “In all paths,  $p$  holds infinitely often”
  - $AG(EFp)$  holds
    - All reachable states  $(s_0, s_1)$  satisfy  $EFp$
  - $AGFp$  does not hold
    - $s_0, s_0, s_0 \dots$  does not satisfy  $GFp$

Hint:



# LTL vs CTL

- The expressive powers of LTL and CTL are incomparable. That is,
  - There is an LTL formula that has no equivalent CTL formula
  - There is a CTL formula that has no equivalent LTL formula
- CTL\* is more expressive than either of them



# Counterexamples

- Counterexample generation is a central feature of MC
- Given  $M$  and  $\varphi$ , such that  $M \not\models \varphi$ , a **counterexample** is a behavior of  $M$ , demonstrating the **violation of  $\varphi$  in  $M$**
- To be useful for debugging it should
  - **have finite representation**
  - **be easy-to-understand by human**
- Simplest form of a counterexample: trace that violates  $\varphi$

# Examples of Counterexamples

- For **AXp**:  
A transition from an initial state to a **state violating p**
  - Counterexample for **AXp** is a witness for **EX¬p**
- For **AGp**:  
A finite path from an initial state to a **state violating p**
  - Counterexample for **AGp** is a witness for **EF¬p**



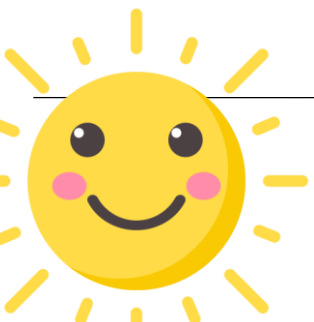
# Examples of Counterexamples

- For **AFp**:  
An infinite path, all of its states **violating p** (satisfying  $\neg p$ )
  - **Counterexample** for **AFp** is a witness for **EG $\neg p$**



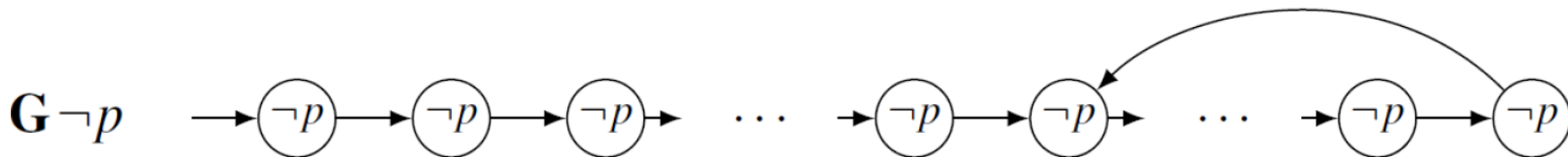
Exercise:

- How do we get a finite representation for the CE?



# Examples of Counterexamples

- For **AFp**:  
An infinite path, all of its states **violating p** (satisfying  $\neg p$ )
  - Counterexample for **AFp** is a witness for **EG $\neg p$**
  
- A finite representation for violation of AFp:
  - A **lasso**, which is a path of the form  $\pi = \pi_0 (\pi_1)^\omega$
  - $\pi_0$  and  $\pi_1$  are **finite paths**
  - $\omega$  indicates infinitely many repetitions of  $\pi_1$



# Safety and Liveness Properties

Informally,

- **Safety** properties guarantee that “something wrong will never happen”
  - Typical example: **AGp**
- **Liveness** properties guarantee that “something good will eventually happen”
  - Typical examples: **AFp**, **A(pUq)**

# Safety Properties

- Nothing “bad” will happen

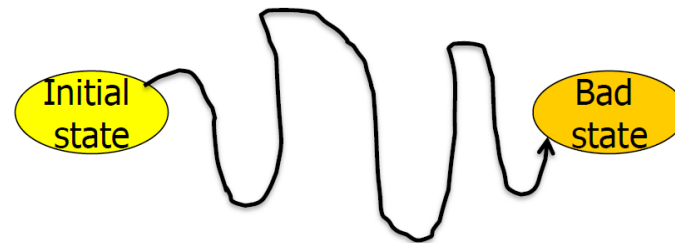


Exercise:

- How does a counterexample for a **safety** property look like?

# Safety Properties

- Nothing “bad” will happen
- Exercise:
  - A counterexample for a safety property is a **finite (loop-free) path**



# Liveness Properties

- Something 'good' will happen.
  - Example:  $F p$



Exercise:

- How does a CE for a **Liveness** property look like?



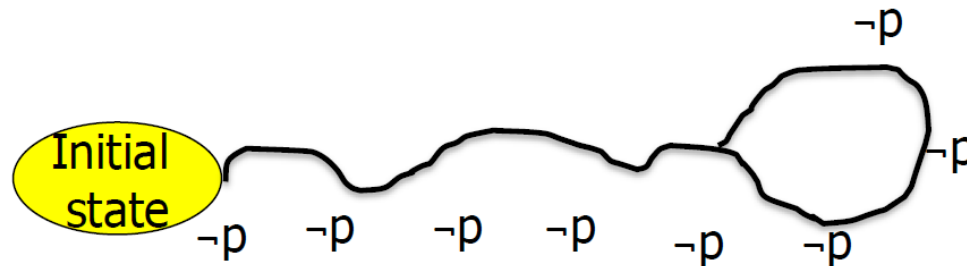
# Liveness Properties

- Something 'good' will happen.
  - Example:  $F p$



Exercise:

- A counterexample is an infinite trace with lasso-shape, showing that this good thing **NEVER** happened



# Part 2 – CTL Model Checking

# The Model Checking Problem

- Given a Kripke structure  $M$  and a CTL formula  $f$
- Model Checking Problem:
  - $M \models f$ , i.e.,  $M$  is a model for  $f$
- Alternative Definition
  - Compute  $\llbracket f \rrbracket_M = \{ s \in S \mid M, s \models f \}$ , i.e., all states satisfying  $f$
  - Check  $S_0 \subseteq \llbracket f \rrbracket_M$  to conclude that  $M \models f$

# Illustrative Example: Mutual Exclusion

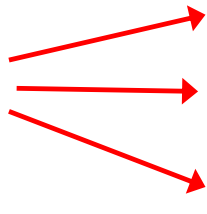
- Two processes with a joint semaphore signal **sem**
- Each process  $P_i$  has a variable  $v_i$  describing its state:
  - $v_i = N$  Non-critical
  - $v_i = T$  Trying
  - $v_i = C$  Critical

# Illustrative Example: Mutual Exclusion

- Each process runs the following program:

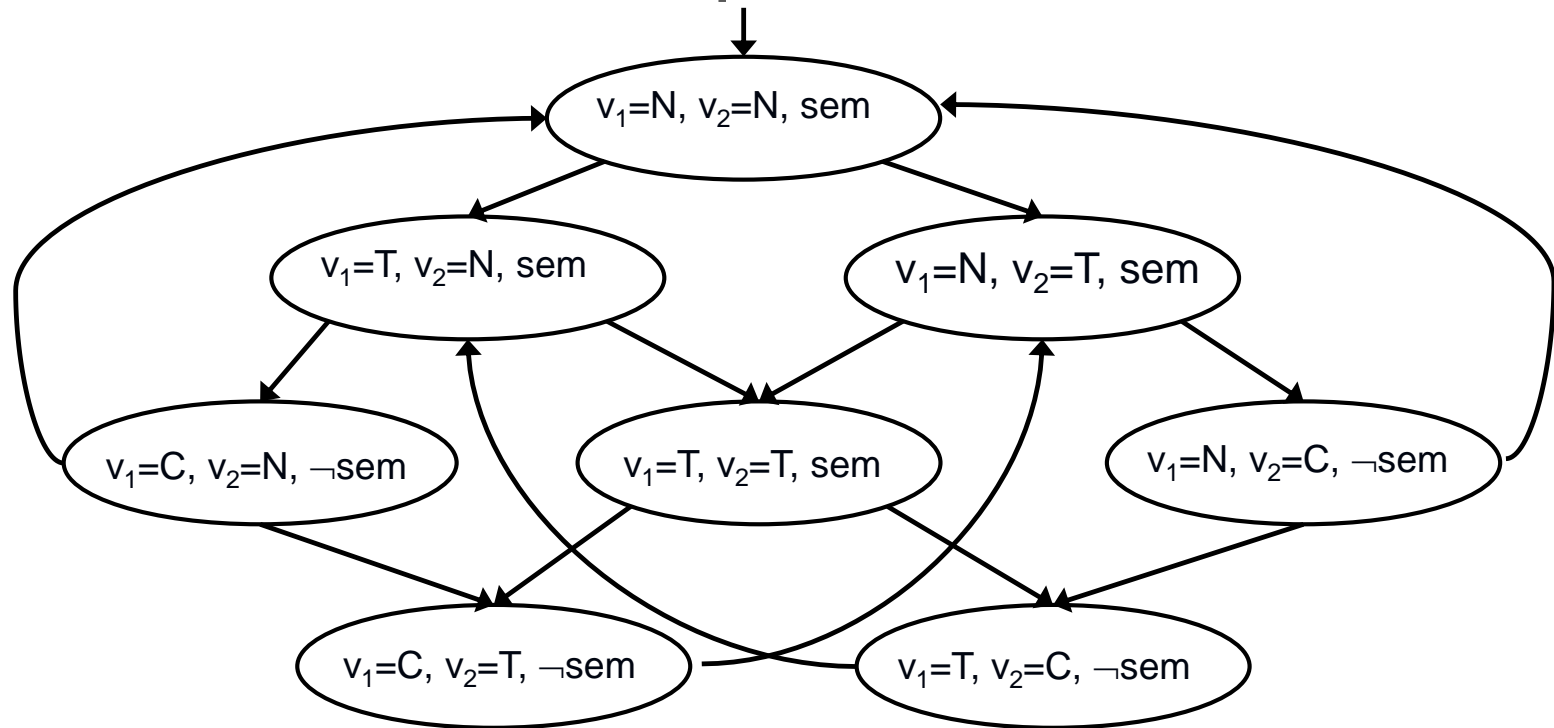
```
Pi :: while (true) {  
    if (vi == N) vi = T;  
    else if (vi == T && sem) { vi = C; sem = 0; }  
    else if (vi == C) { vi = N; sem = 1; }  
}
```

Atomic  
action



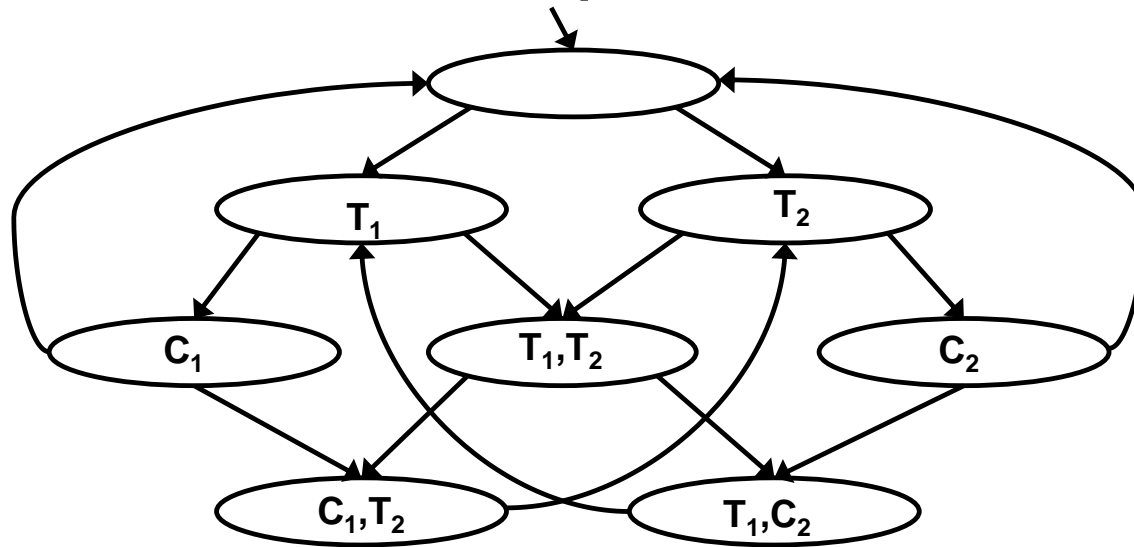
- The full program is:  $P_1 || P_2$
- Initial state:  $(v_1=N, v_2=N, sem)$
- The execution is interleaving

# Illustrative Example: Mutual Exclusion



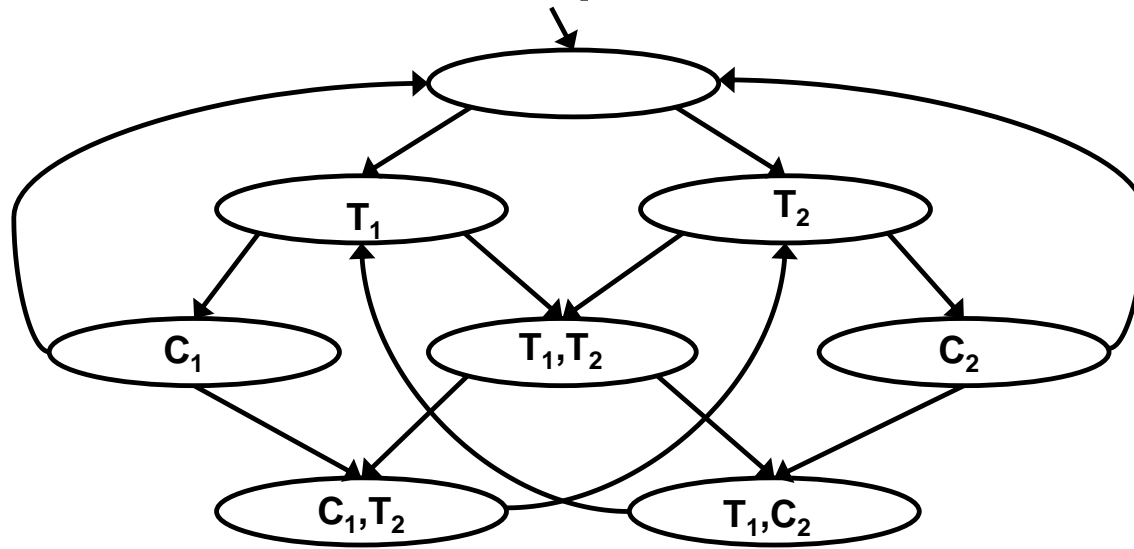
- We define atomic propositions:  $AP=\{C_1, C_2, T_1, T_2\}$
- A state is labeled with  $T_i$  if  $v_i=T$
- A state is labeled with  $C_i$  if  $v_i=C$

# Illustrative Example: Mutual Exclusion



- We define atomic propositions:  $AP = \{C_1, C_2, T_1, T_2\}$
- A state is labeled with  $T_i$  if  $v_i = T$
- A state is labeled with  $C_i$  if  $v_i = C$

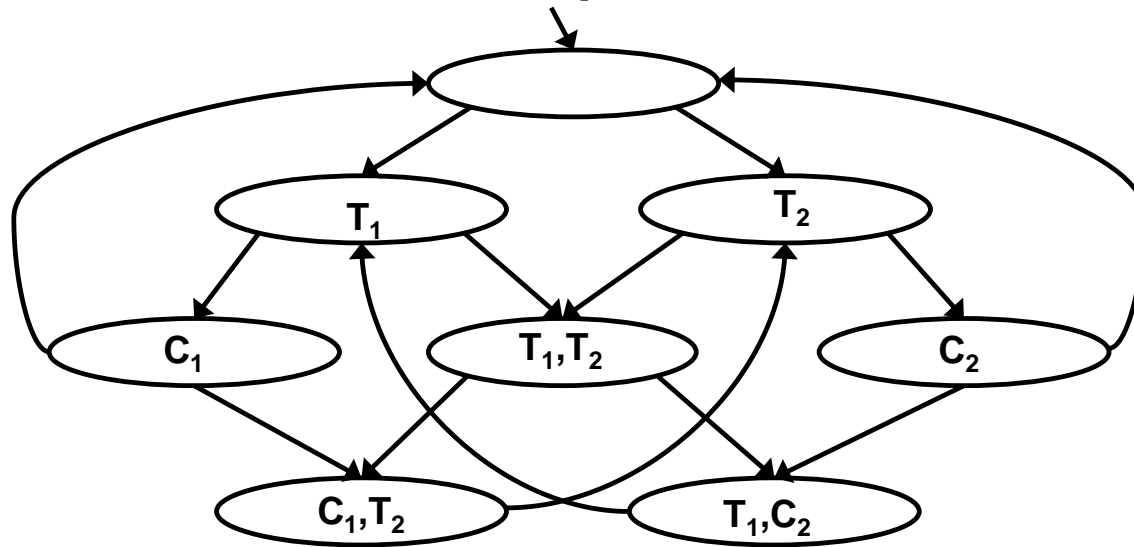
# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 1:  $f := \mathbf{AG}\neg(C_1 \wedge C_2)$
  - Compute  $\llbracket f \rrbracket_M = \{ s \in S \mid M, s \models f \}$  and check  $S_0 \subseteq \llbracket f \rrbracket_M$

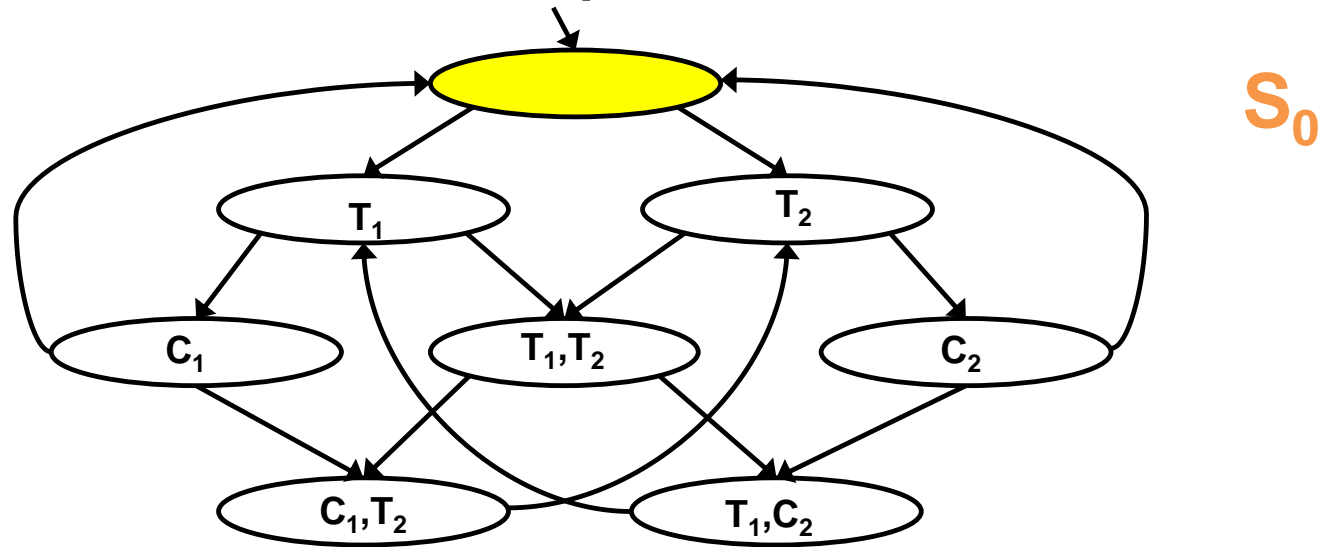


# Illustrative Example: Mutual Exclusion



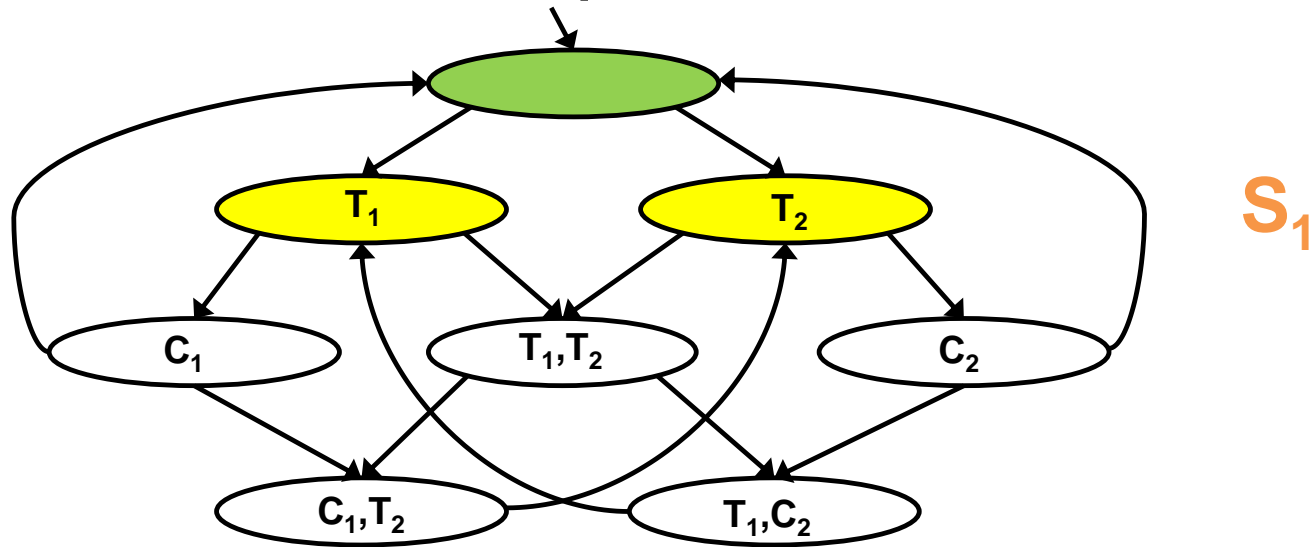
- Does it hold that  $M \models f$ ?
  - Property 1:  $f := \mathbf{AG}\neg(C_1 \wedge C_2)$
- $S_i \equiv$  reachable states from an initial state after  $i$  steps

# Illustrative Example: Mutual Exclusion



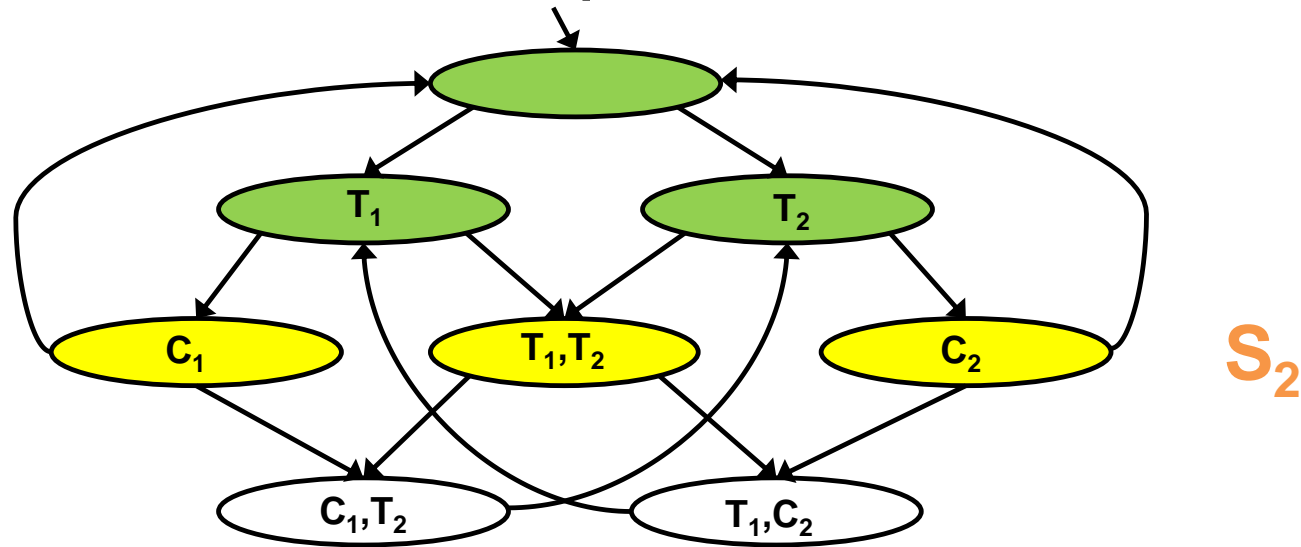
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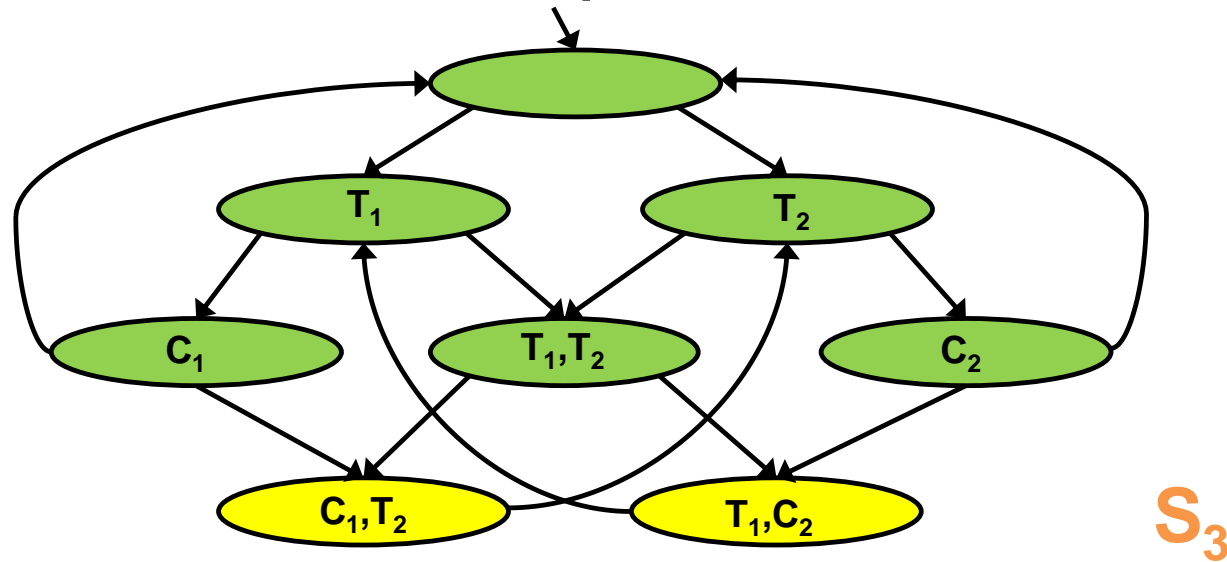
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# Illustrative Example: Mutual Exclusion



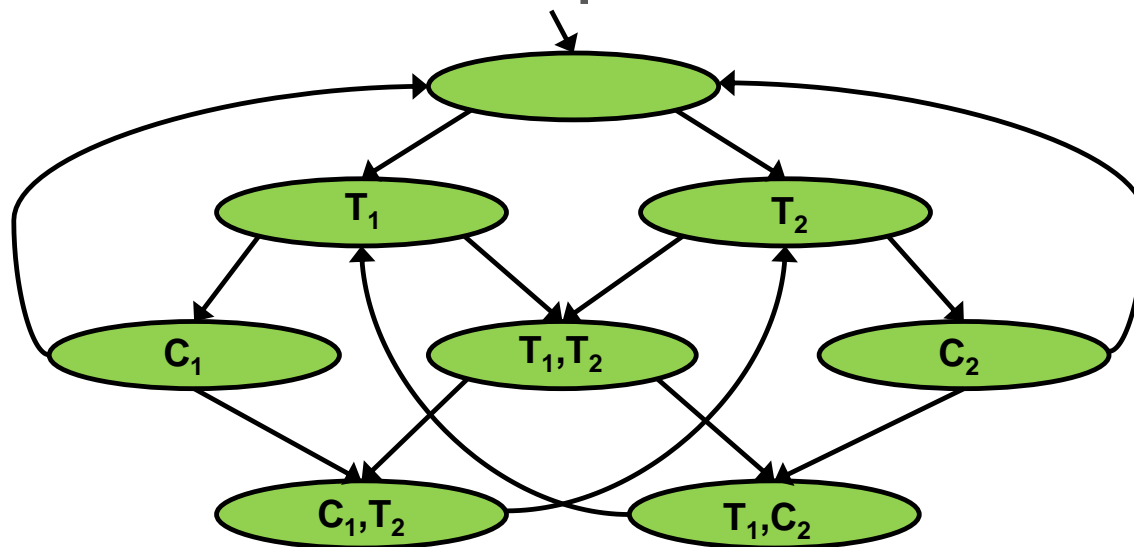
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# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
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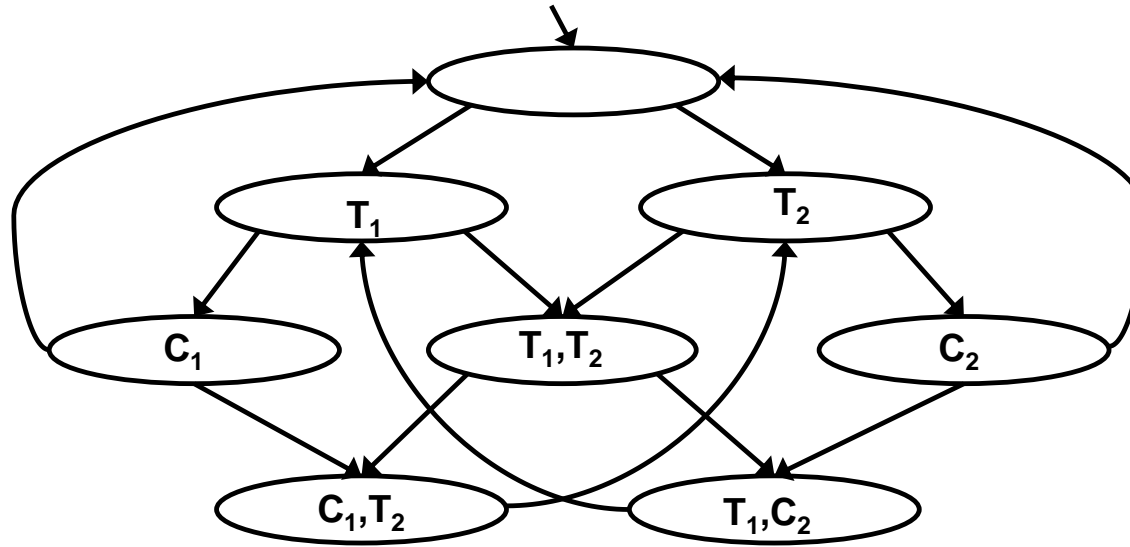
# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 1:  $f := \mathbf{AG} \neg (C_1 \wedge C_2)$  ✓  $M \models \mathbf{AG} \neg (C_1 \wedge C_2)$

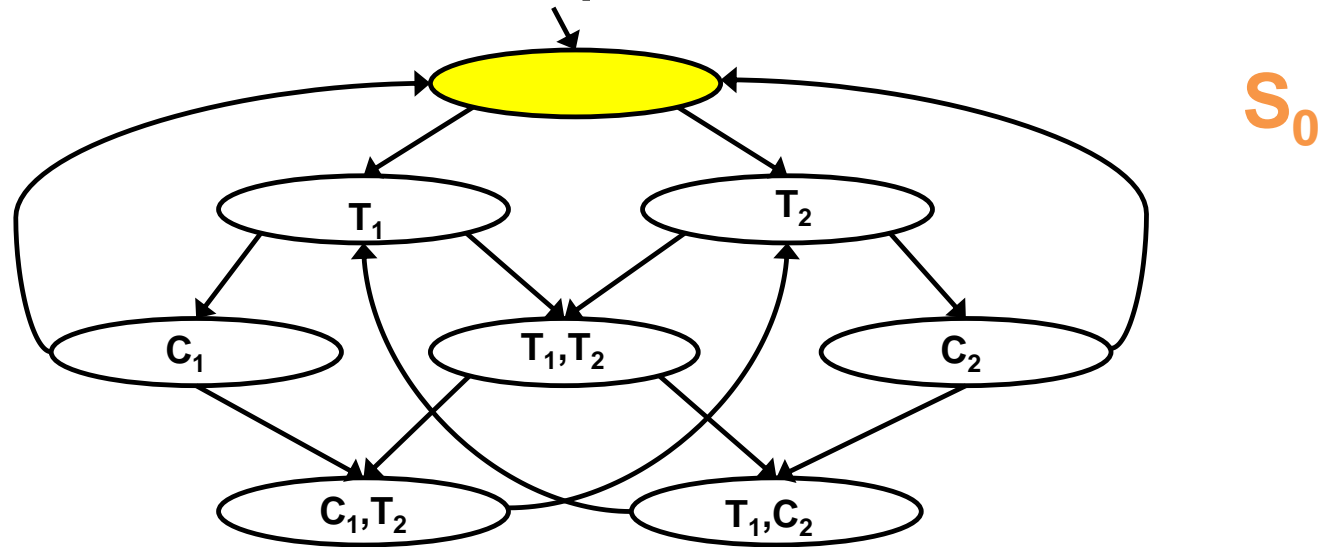


# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 2:  $f := \mathbf{AG}\neg(T_1 \wedge T_2)$

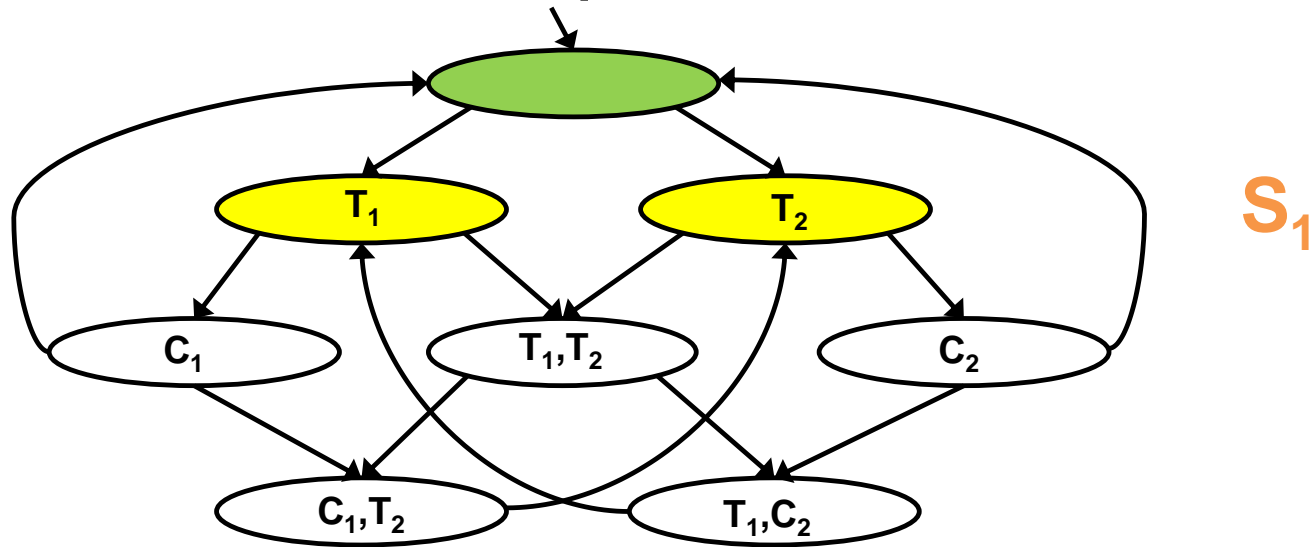
# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 2:  $f := \mathbf{AG}\neg(T_1 \wedge T_2)$
- $S_i \equiv$  reachable states from an initial state after  $i$  steps

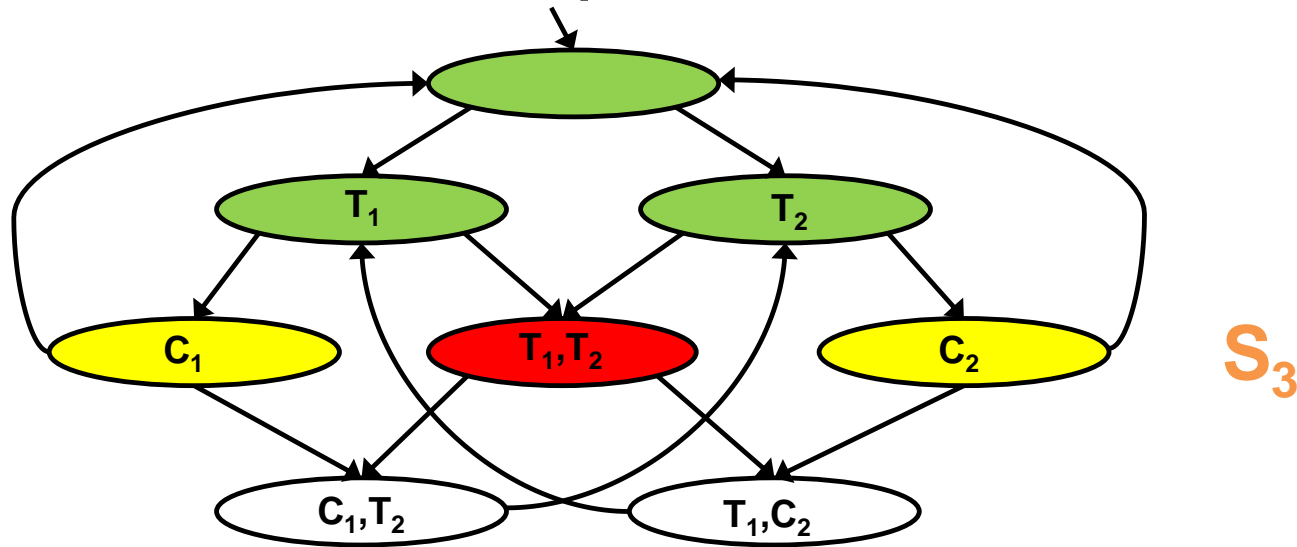


# Illustrative Example: Mutual Exclusion

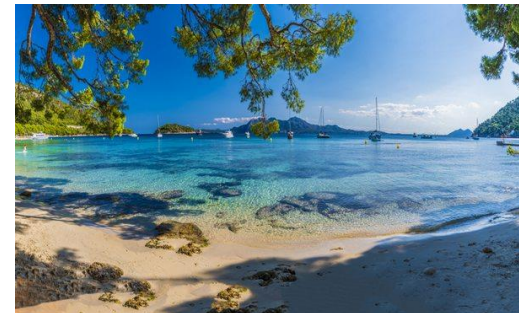


- Does it hold that  $M \models f$ ?
  - Property 2:  $f := \mathbf{AG}\neg(T_1 \wedge T_2)$
- $S_i \equiv$  reachable states from an initial state after  $i$  steps

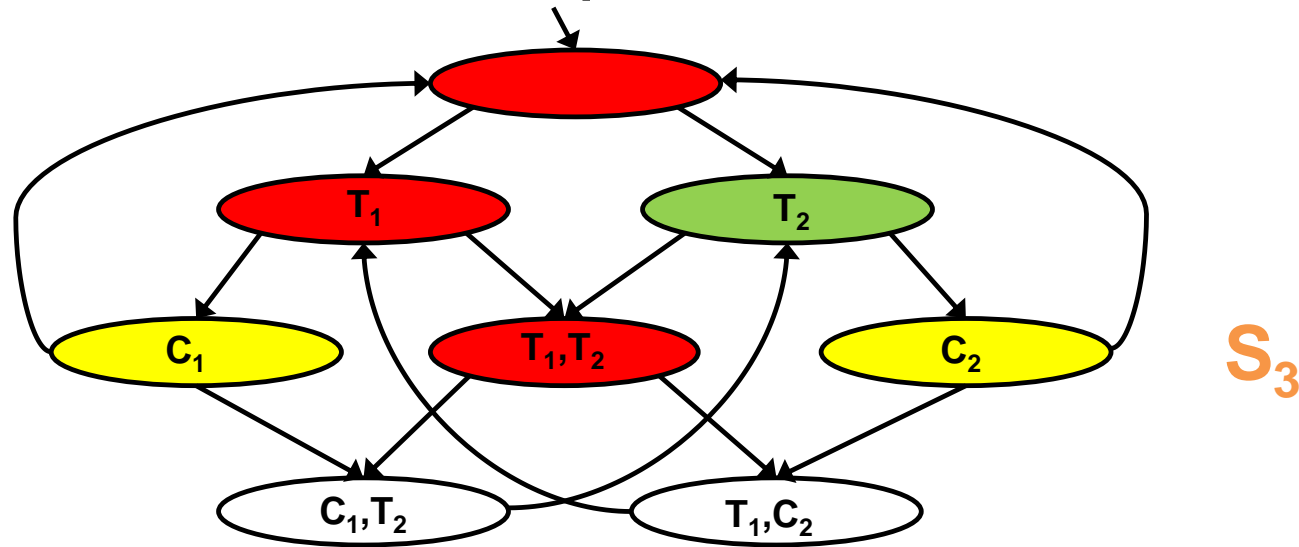
# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 2:  $f := \mathbf{AG}\neg(T_1 \wedge T_2)$   ~~$\times$~~   $M \not\models \mathbf{AG}\neg(T_1 \wedge T_2)$

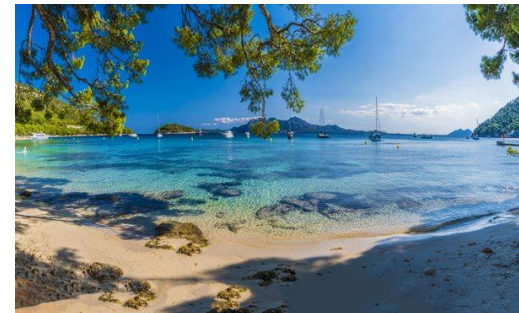


# Illustrative Example: Mutual Exclusion

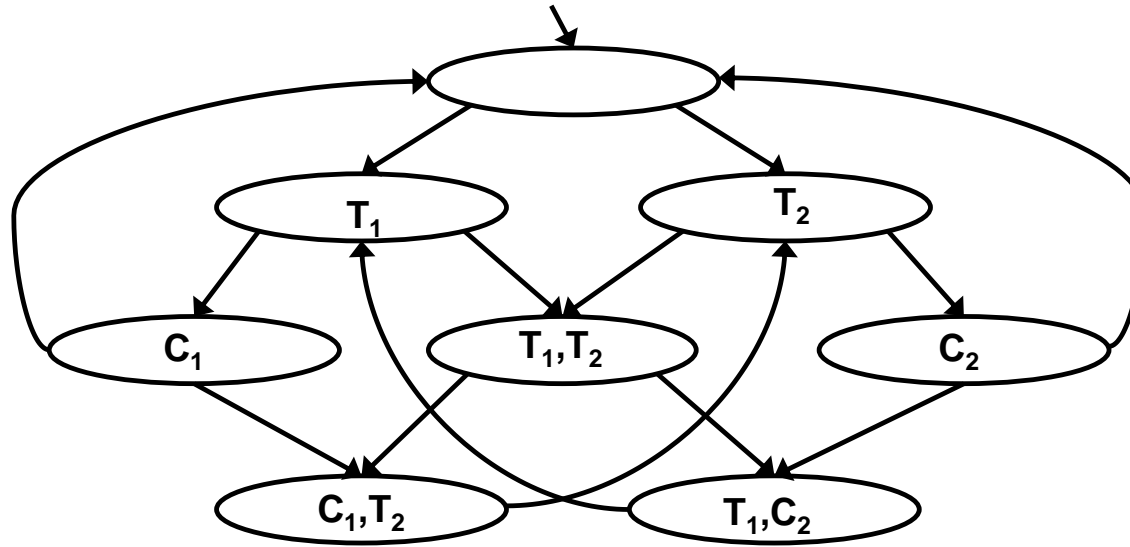


- Does it hold that  $M \models f$ ?
  - Property 2:  $f := \mathbf{AG} \neg (T_1 \wedge T_2)$   ~~$\times$~~   $M \not\models \mathbf{AG} \neg (T_1 \wedge T_2)$

- Model checker returns a **counterexample**

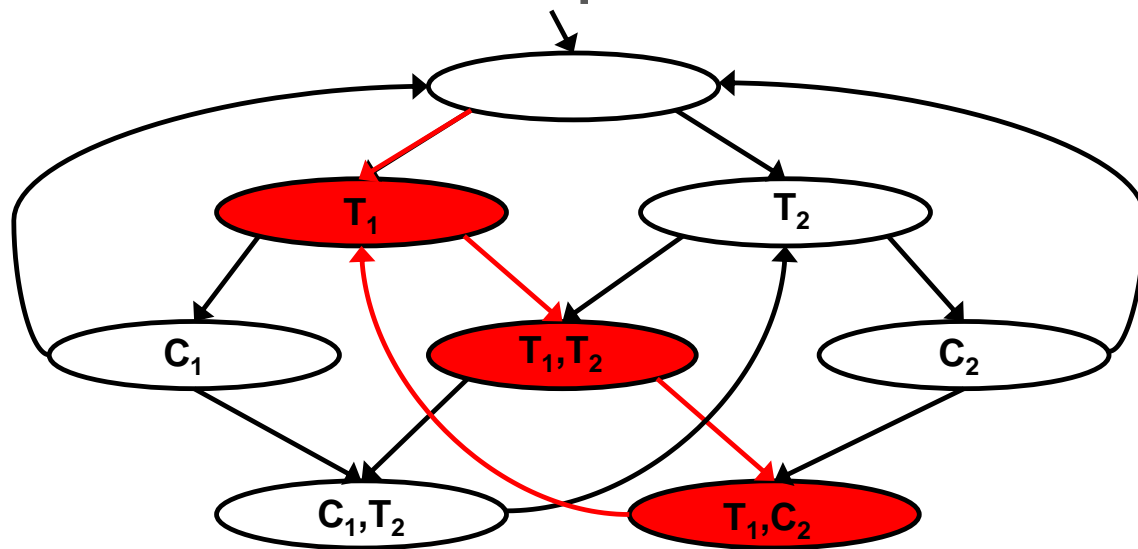


# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 3:  $f := \mathbf{AG} ((T_1 \rightarrow \mathbf{F} C_1) \wedge (T_2 \rightarrow \mathbf{F} C_2))$
- In case  $M \not\models f$ , compute a counterexample

# Illustrative Example: Mutual Exclusion

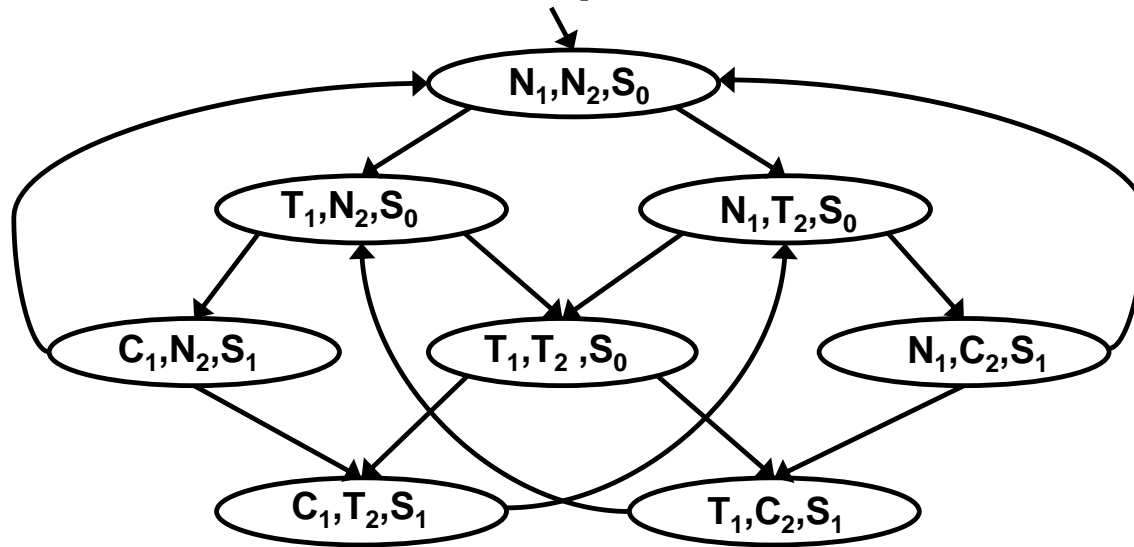


- Does it hold that  $M \models f$ ?
  - Property 3:  $f := \mathbf{AG} ((T_1 \rightarrow \mathbf{F} C_1) \wedge (T_2 \rightarrow \mathbf{F} C_2))$
- In case  $M \not\models f$ , compute a counterexample

**X**  $M \not\models \mathbf{AG} ((T_1 \rightarrow \mathbf{F} C_1) \wedge (T_2 \rightarrow \mathbf{F} C_2))$

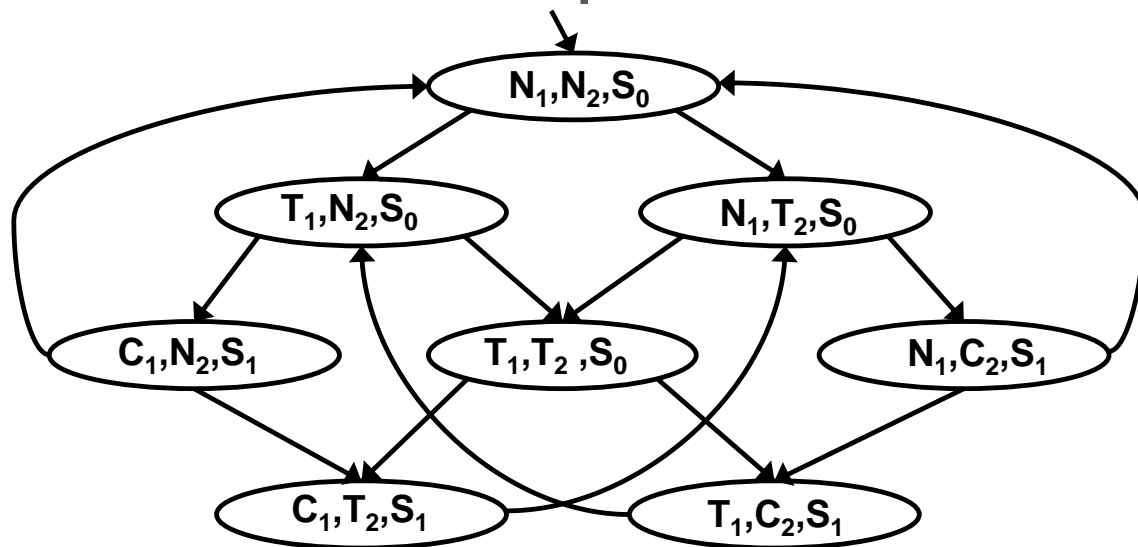


# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ?
  - Property 4:  $f := \text{AG EF } (N_1 \wedge N_2 \wedge S_0)$
- How would you express property 4 in natural language?
- In case  $M \not\models f$ , compute a counterexample

# Illustrative Example: Mutual Exclusion



- Does it hold that  $M \models f$ ? ✓
  - Property 4:  $f := \mathbf{AG EF} (N_1 \wedge N_2 \wedge S_0)$
- *No matter where you are there is always a way to get to the initial state (restart)*



# CTL Model Checking

Receives:

- A Kripke structure  $M$ , modeling a system
- A CTL formula  $f$ , describing a property
- Determines whether  $M \models f$
- Alternatively definition, MC returns  $\llbracket f \rrbracket = \{ s \in S \mid M, s \models f \}$ 
  - $M$  is omitted from  $\llbracket f \rrbracket_M$  when clear from the context



# CTL Model Checking $M \models f$

Iterative algorithm:

Compute  $\llbracket g \rrbracket_M$  for every subformula  $g$  of  $f$

- Work **iteratively** on **subformulas** of  $f$ 
  - from **simpler** to **complex** subformulas
- For checking  **$AG(\text{request} \rightarrow AF \text{grant})$** 
  - Check **grant, request**
  - Then check  **$AF \text{grant}$**
  - Next check  **$\text{request} \rightarrow AF \text{grant}$**
  - Finally check  **$AG(\text{request} \rightarrow AF \text{grant})$**

# CTL Model Checking $M \models f$

- For each  $s$ , computes  $\text{label}(s)$ , which is the set of subformulas of  $f$  that are true in  $s$
- We check subformula  $g$  of  $f$  only after all subformulas of  $g$  have already been checked
- For subformula  $g$ , the algorithm adds  $g$  to  $\text{label}(s)$  for every state  $s$  that satisfies  $g$
- When we finish checking  $g$ , the following holds:
  - $g \in \text{label}(s) \Leftrightarrow M, s \models g$

# CTL Model Checking $M \models f$

- For each  $s$ , computes  $\text{label}(s)$ , which is the set of subformulas of  $f$  that are true in  $s$
- $M \models f$  if and only if  $f \in \text{label}(s)$  for all initial states  $s$  of  $M$ 
  - $M \models f$  if and only if  $S_0 \subseteq \llbracket f \rrbracket_M$


# Minimal set of operators for CTL

- All CTL formulas can be transformed to use only the operators:
  - $\neg$ ,  $\vee$ , **EX**, **EU**, **EG**
- MC algorithm needs to handle **AP** (atomic propositions) and  $\neg$ ,  $\vee$ , **EX**, **EU**, **EG**

# Model Checking Atomic Propositions

- Procedure for **labeling** the states satisfying  $p \in AP$ :

$$p \in \text{label}(s) \Leftrightarrow p \in L(s)$$

  
Defined by M

# Model Checking $\neg$ , $\vee$ - Formulas

- Let  $f_1$  and  $f_2$  be subformulas that have already been checked
  - added to label(s), when needed



Give the procedures for **labeling** the states satisfying  $\neg f_1$  and  $f_1 \vee f_2$

# Model Checking $\neg$ , $\vee$ - Formulas



- Let  $f_1$  and  $f_2$  be subformulas that have already been checked
  - added to  $label(s)$ , when needed
- Give the procedures for **labeling** the states satisfying  $\neg f_1$  and  $f_1 \vee f_2$ 
  - $\neg f_1$  add to  $label(s)$  if and only if  $f_1 \notin label(s)$
  - $f_1 \vee f_2$  add to  $label(s)$  if and only if  $f_1 \in labels(s)$  **or**  $f_2 \in label(s)$

# Model Checking $g = EX f_1$

 Give the procedures for **labeling** states satisfying  $EX f_1$



# Model Checking $g = EX f_1$

- Give the procedures for **labeling** states satisfying  $EX f_1$ 
  - Add  $g$  to  $label(s)$  if and only if  $s$  has a successor  $t$  such that  $f_1 \in label(t)$



# Model Checking $g = EX f_1$

- Give the procedures for **labeling** states satisfying  $EX f_1$ 
  - Add  $g$  to  $label(s)$  if and only if  $s$  has a successor  $t$  such that  $f_1 \in label(t)$

```
procedure CheckEX ( $f_1$ )
```

```
   $T := \{ t \mid f_1 \in label(t) \}$ 
```

```
  while  $T \neq \emptyset$  do
```

```
    choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;
```

```
    for all  $s$  such that  $R(s,t)$  do
```

```
      if  $EX f_1 \notin label(s)$  then
```

```
         $label(s) := label(s) \cup \{ EX f_1 \}$ ;
```



# Model Checking $g = E(f_1 U f_2)$

 Procedures for **labeling** states satisfying  $E(f_1 U f_2)$

- Think how you can rewrite the procedure CheckEX

```
procedure CheckEX ( $f_1$ )
```

```
  T := { t |  $f_1 \in \text{label}(t)$  }
```

```
while T  $\neq \emptyset$  do
```

```
  choose t  $\in$  T; T := T \ {t};
```

```
  for all s such that R(s,t) do
```

```
    if EX  $f_1 \notin \text{label}(s)$  then
```

```
      label(s) := label(s)  $\cup$  { EX  $f_1$ };
```

```
procedure CheckEU ( $f_1, f_2$ )
```

```
  T :=
```

```
  for all t  $\in$  T do
```

```
    label(t) :=
```

```
while T  $\neq \emptyset$  do
```

```
  choose t  $\in$  T; T := T \ {t};
```

```
  for all s such that R(s,t) do
```



# Model Checking $g = E(f_1 U f_2)$

- Procedures for **labeling** states satisfying  $E(f_1 U f_2)$ 
  - Rewriting the procedure CheckEX

```
procedure CheckEX ( $f_1$ )
```

```
   $T := \{ t \mid f_1 \in \text{label}(t) \}$ 
```

```
while  $T \neq \emptyset$  do
```

```
  choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;
```

```
  for all  $s$  such that  $R(s,t)$  do
```

```
    if  $EX f_1 \notin \text{label}(s)$  then
```

```
       $\text{label}(s) := \text{label}(s) \cup \{ EX f_1 \}$ ;
```

```
procedure CheckEU ( $f_1, f_2$ )
```

```
   $T := \{ t \mid f_2 \in \text{label}(t) \}$ 
```

```
for all  $t \in T$  do
```

```
   $\text{label}(t) := \text{label}(t) \cup \{ E(f_1 U f_2) \}$ 
```

```
while  $T \neq \emptyset$  do
```

```
  choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;
```

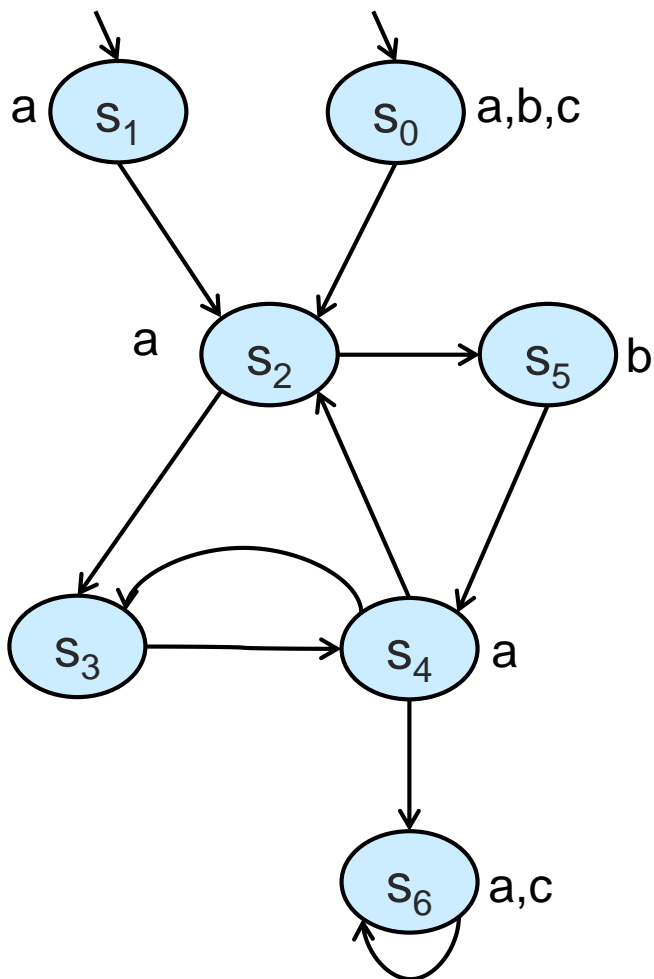
```
  for all  $s$  such that  $R(s,t)$  do
```

```
    if  $E(f_1 U f_2) \notin \text{label}(s)$  and  $f_1 \in \text{label}(s)$  then
```

```
       $\text{label}(s) := \text{label}(s) \cup \{ E(f_1 U f_2) \}$ ;
```

```
       $T := T \cup \{s\}$ 
```

# Example: Model Checking $U$ Formulas



Does it hold that  $M \models f$ ?

- $f := E(aUb)$

procedure CheckEU ( $f_1, f_2$ )

$T := \{ t \mid f_2 \in \text{label}(t) \}$

for all  $t \in T$  do

label( $t$ ) := label( $t$ )  $\cup$  {  $E(f_1 \cup f_2)$  }

while  $T \neq \emptyset$  do

choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;

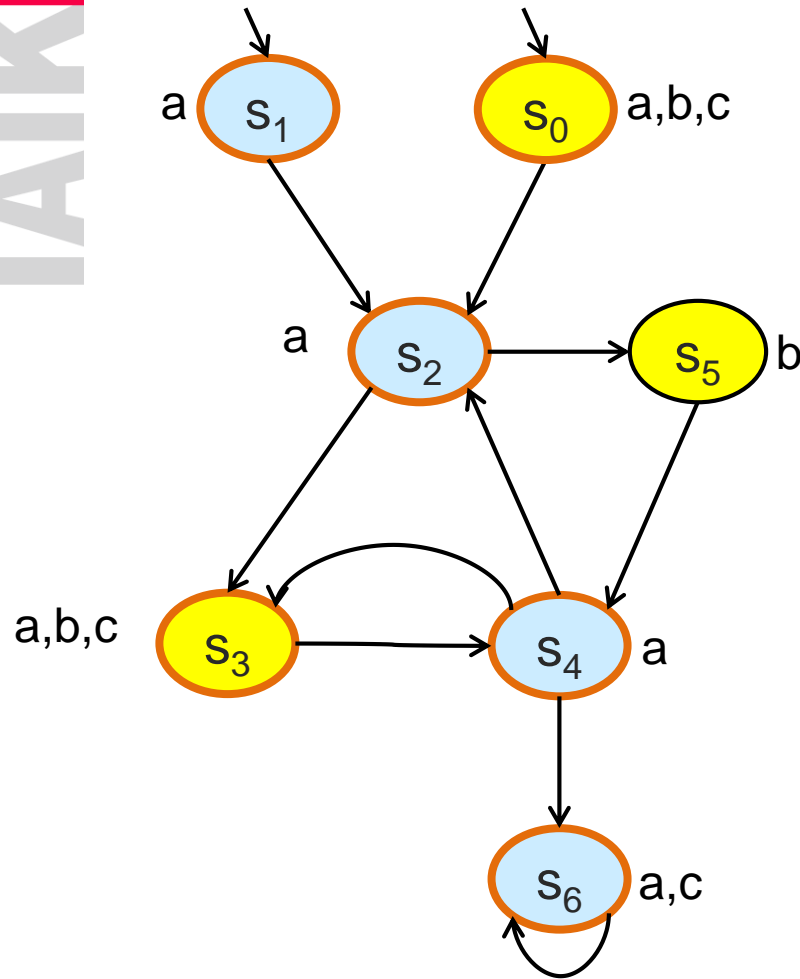
for all  $s$  such that  $R(s, t)$  do

if  $E(f_1 \cup f_2) \notin \text{label}(s)$  and  $f_1 \in \text{label}(s)$  then

label( $s$ ) := label( $s$ )  $\cup$  {  $E(f_1 \cup f_2)$  };

$T := T \cup \{s\}$

# Example: Model Checking $U$ Formulas



Does it hold that  $M \models f$ ?

- $f := E(aUb)$

procedure CheckEU ( $f_1, f_2$ )

$T := \{ t \mid f_2 \in \text{label}(t) \}$

for all  $t \in T$  do

$\text{label}(t) := \text{label}(t) \cup \{ E(f_1 \cup f_2) \}$

while  $T \neq \emptyset$  do

  choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;

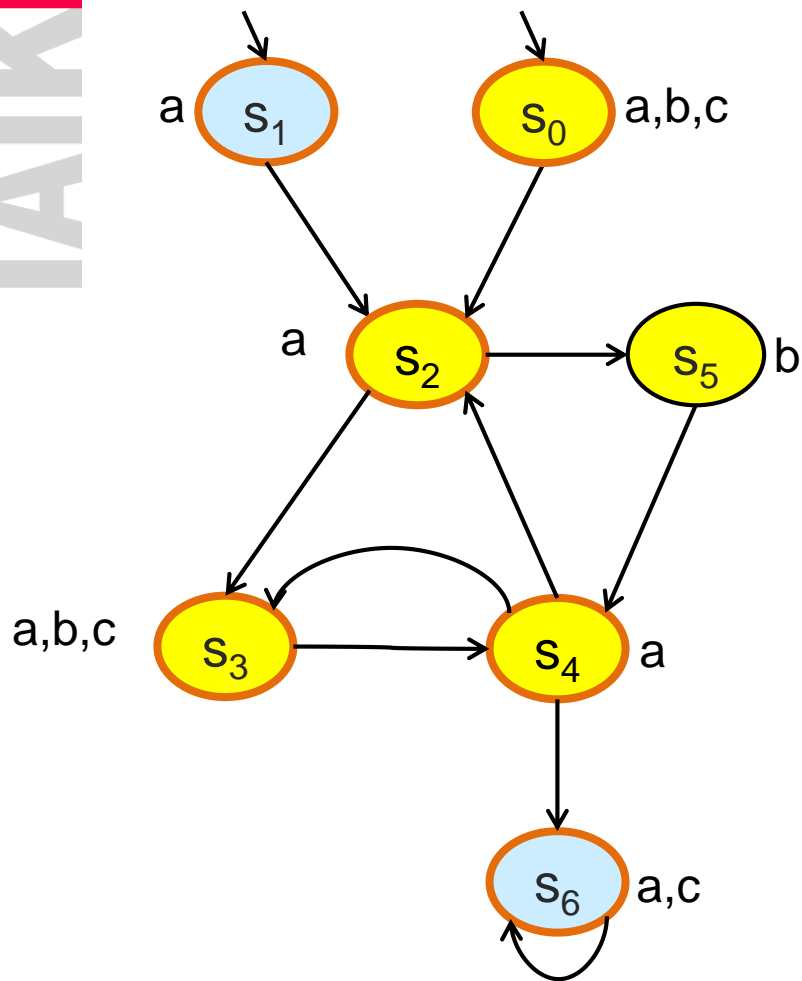
  for all  $s$  such that  $R(s,t)$  do

    if  $E(f_1 \cup f_2) \notin \text{label}(s)$  and  $f_1 \in \text{label}(s)$  then

$\text{label}(s) := \text{label}(s) \cup \{ E(f_1 \cup f_2) \}$ ;

$T := T \cup \{s\}$

# Example: Model Checking $U$ Formulas



Does it hold that  $M \models f$ ?

- $f := E(aUb)$

```
procedure CheckEU ( $f_1, f_2$ )
```

```
   $T := \{ t \mid f_2 \in \text{label}(t) \}$ 
```

```
  for all  $t \in T$  do
```

```
     $\text{label}(t) := \text{label}(t) \cup \{ E(f_1 \cup f_2) \}$ 
```

```
  while  $T \neq \emptyset$  do
```

```
    choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;
```

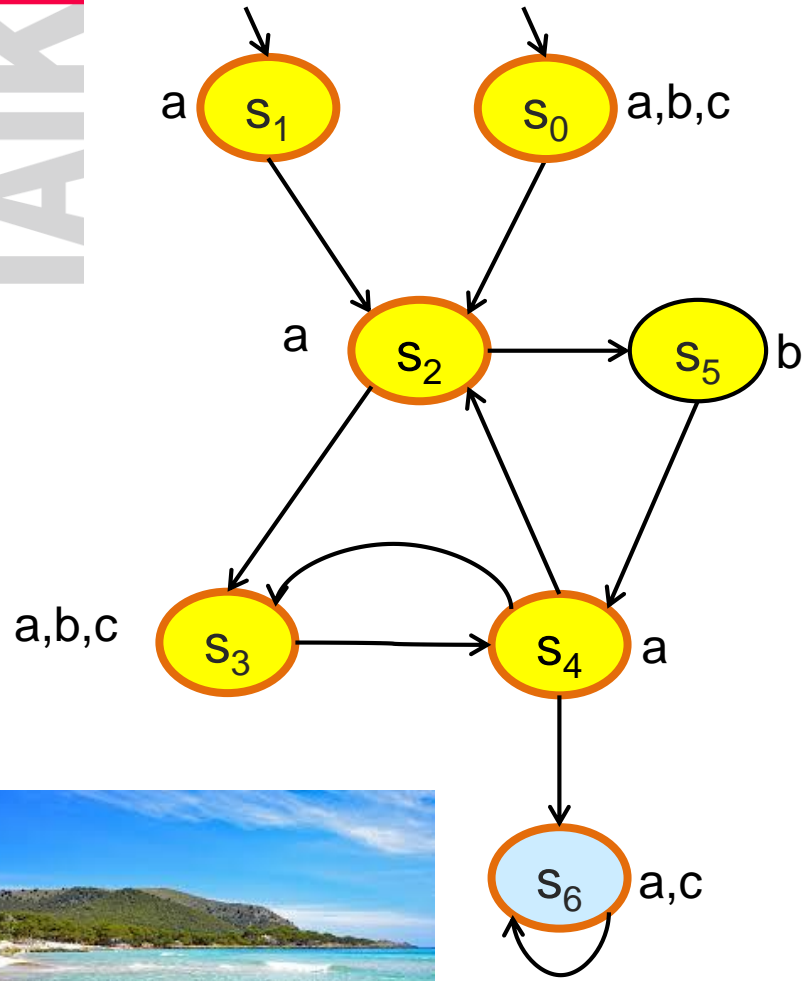
```
    for all  $s$  such that  $R(s, t)$  do
```

```
      if  $E(f_1 \cup f_2) \notin \text{label}(s)$  and  $f_1 \in \text{label}(s)$  then
```

```
         $\text{label}(s) := \text{label}(s) \cup \{ E(f_1 \cup f_2) \}$ ;
```

```
         $T := T \cup \{s\}$ 
```

# Example: Model Checking $U$ Formulas



Does it hold that  $M \models f$ ?

- $f := E(aUb)$

✓  $M \models E(aUb)$

$[[E(aUb)]] = \{0,3,5,4\}$

```

    procedure CheckEU (f1,f2)
      T := { t | f2 ∈ label(t) }

      for all t ∈ T do
        label(t) := label(t) ∪ { E(f1 U f2) }

      while T ≠ ∅ do
        choose t ∈ T; T := T \ {t};
        for all s such that R(s,t) do
          if E(f1 U f2) ∉ label(s) and f1 ∈ label(s) then
            label(s) := label(s) ∪ { E(f1 U f2) };
            T := T ∪ {s}
  
```



# Model Checking $g = EGf_1$

Observation:

$s \models \mathbf{EG} f_1$

iff

There is a path  $\pi$ , starting at  $s$ , such that  $\pi \models \mathbf{G} f_1$

iff

There is a path from  $s$  to a **strongly connected component**, where all states satisfy  $f_1$

# Model Checking $g = EGf_1$

- A Strongly Connected Component (SCC) in a graph is a subgraph  $C$  such that every node in  $C$  is reachable from any other node in  $C$  via nodes in  $C$
- An SCC  $C$  is maximal (MSCC) if it is not contained in any other SCC in the graph
  - Possible to find all MSCC in linear time  $O(|S|+|R|)$  (Tarjan)
- $C$  is nontrivial if it contains at least one edge. Otherwise, it is trivial

# Model Checking $g = EGf_1$

- Reduced structure for  $M$  and  $f_1$ :
  - Remove from  $M$  all states such that  $f_1 \notin \text{label}(s)$
- Resulting model:  $M' = (S', R', L')$ 
  - $S' = \{ s \mid M, s \models f_1 \}$
  - $R' = (S' \times S') \cap R$
  - $L'(s') = L(s')$  for every  $s' \in S'$
- Theorem:  $M, s \models EG f_1$  iff
  1.  $s \in S'$  and
  2. There is a path in  $M'$  from  $s$  to some state  $t$  in a nontrivial MSCC of  $M'$

# Model Checking $g = EG f_1$

```
procedure CheckEG ( $f_1$ )
```

```
   $S' := \{s \mid f_1 \in \text{label}(s)\}$ 
```

```
   $\text{MSCC} := \{C \mid C \text{ is a nontrivial MSCC of } M'\}$ 
```

```
   $T := \cup_{C \in \text{MSCC}} \{s \mid s \in C\}$ 
```

```
  for all  $t \in T$  do
```

```
     $\text{label}(t) := \text{label}(t) \cup \{EG f_1\}$ 
```

```
  while  $T \neq \emptyset$  do
```

```
    choose  $t \in T$ ;  $T := T \setminus \{t\}$ ;
```

```
    for all  $s \in S'$  such that  $R'(s,t)$  do
```

```
      if  $EG f_1 \notin \text{label}(s)$  then
```

```
         $\text{label}(s) := \text{label}(s) \cup \{EG f_1\}$ ;
```

```
         $T := T \cup \{s\}$ 
```



# Model Checking Complexity

## Steps per Subformula

- MC Atomic Propositions
  -
- MC  $\neg$ ,  $\vee$  formulas
  -
- MC  $g = EX f_1$ 
  -
- MC  $g = E(f_1 U f_2)$ 
  -
- MC  $g = EG f_1$



# Model Checking Complexity

## Steps per Subformula

- MC Atomic Propositions
  - $O(|S|)$  steps
- MC  $\neg, \vee$  formulas
  - $O(|S|)$  steps
- MC  $g = EX f_1$ 
  - Add  $g$  to label( $s$ ) iff  $s$  has a successor  $t$  such that  $f_1 \in \text{label}(t)$
  - $O(|S| + |R|)$
- MC  $g = E(f_1 U f_2)$ 
  - $O(|S| + |R|)$
- MC  $g = EG f_1$



# Model Checking Complexity

## Steps per Subformula

- $MC\ g = EGf_1$ 
  - Computing  $M'$  :  $O(|S| + |R|)$
  - Computing MSCCs using Tarjan's algorithm:  
 $O(|S'| + |R'|)$
  - Labeling all states in MSCCs:  $O(|S'|)$
  - Backward traversal:  $O(|S'| + |R'|)$
- $\Rightarrow$  Overall:  $O(|S| + |R|)$

# Model Checking Complexity

## Steps per Subformula

- MC Atomic Propositions
  - $O(|S|)$  steps
- MC  $\neg, \vee$  formulas
  - $O(|S|)$  steps
- MC  $g = EX f_1$ 
  - Add  $g$  to label( $s$ ) iff  $s$  has a successor  $t$  such that  $f_1 \in \text{label}(t)$
  - $O(|S| + |R|)$
- MC  $g = E(f_1 U f_2)$ 
  - $O(|S| + |R|)$
- MC  $g = EG f_1$ 
  - $O(|S| + |R|)$



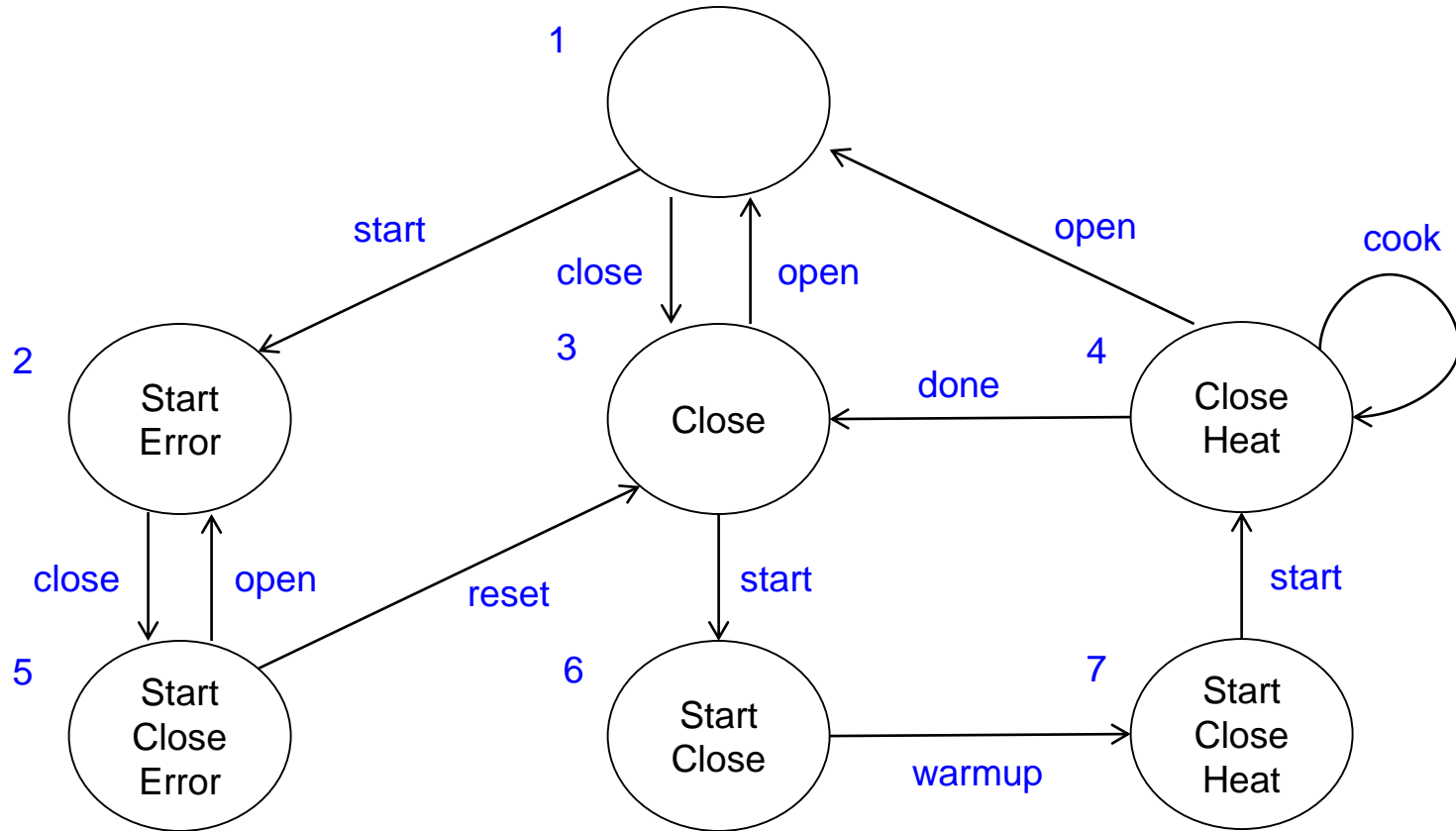
# Model Checking Complexity



- Each subformula
  - $O(|S| + |R|) = O(|M|)$
- Number of subformulas in  $f$ :
  - $O(|f|)$
- Total
  - $O(|M| \times |f|)$
  
- For comparison
  - Complexity of MC for LTL and CTL\* is  $O(|M| \times 2^{|f|})$

# Microwave Example

- Use the proposed algorithm to compute if  $M \models f$ ?
  - $f := AG (Start \rightarrow AF Heat)$



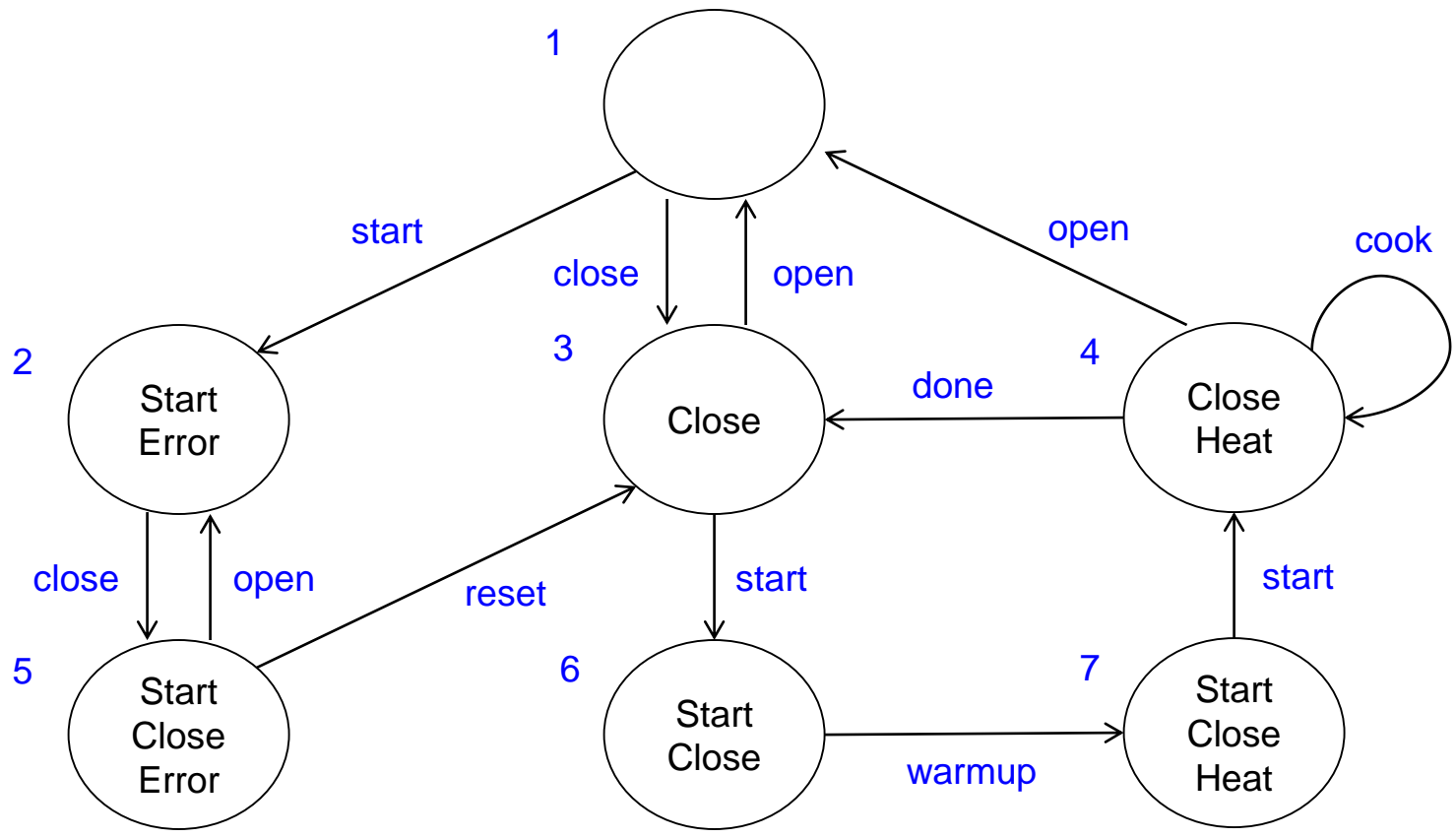
# Microwave Example

- Step 1: Rewrite the formula
  - $AG (\text{Start} \rightarrow AF \text{Heat}) \equiv$
  - $\neg EF (\text{Start} \wedge EG \neg \text{Heat}) \equiv$
  - $\neg E (\text{true} \cup (\text{Start} \wedge EG \neg \text{Heat}))$



# Microwave Example

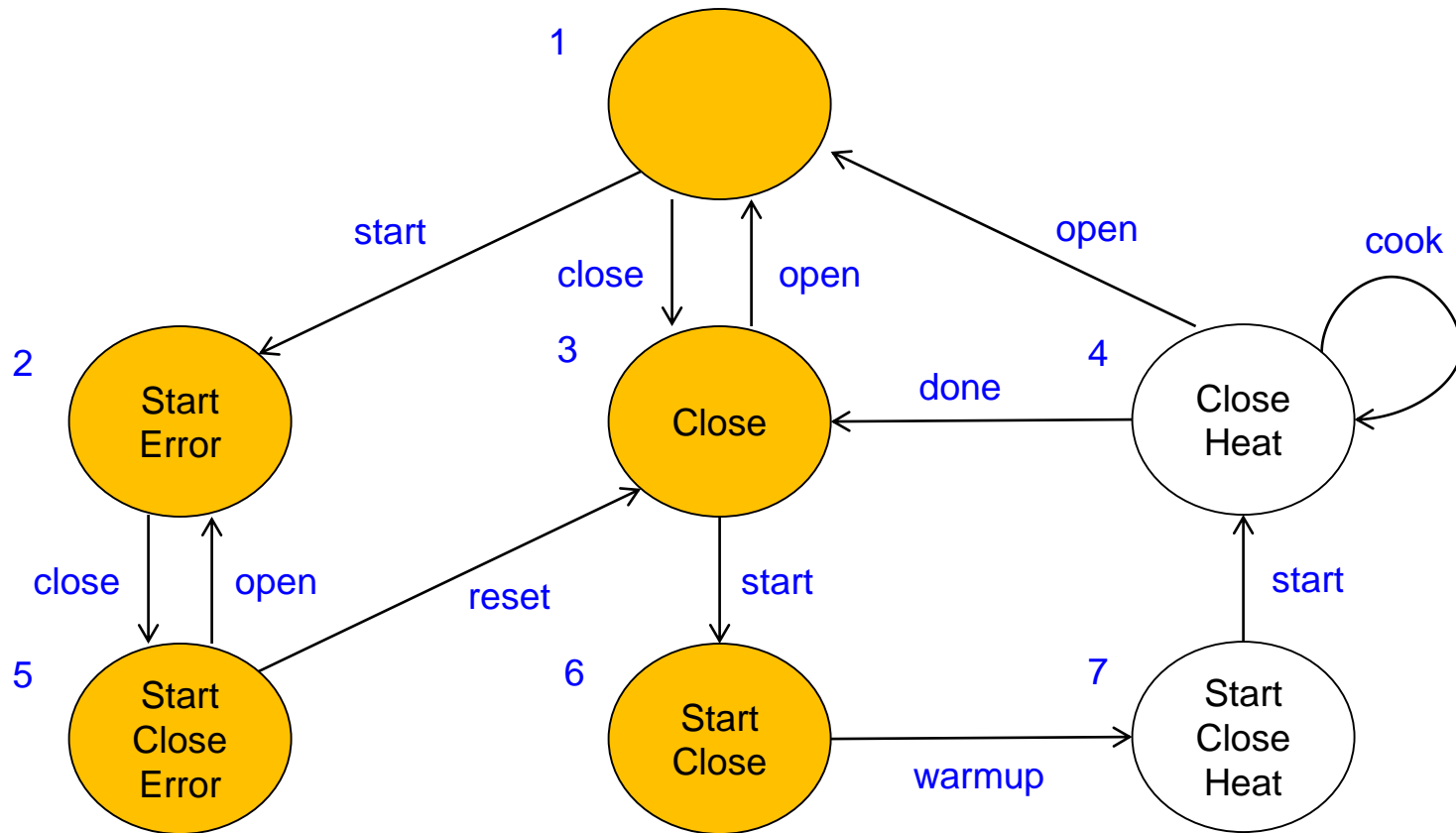
- Use the proposed algorithm to compute if  $M \models f$ ?
  - $f := \neg E (\text{true} \cup (\text{Start} \wedge \text{EG} \neg \text{Heat}))$



$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

$[[start]] = \{2,5,6,7\}$

$[[\neg Heat]] = \{1,2,3,5,6\}$



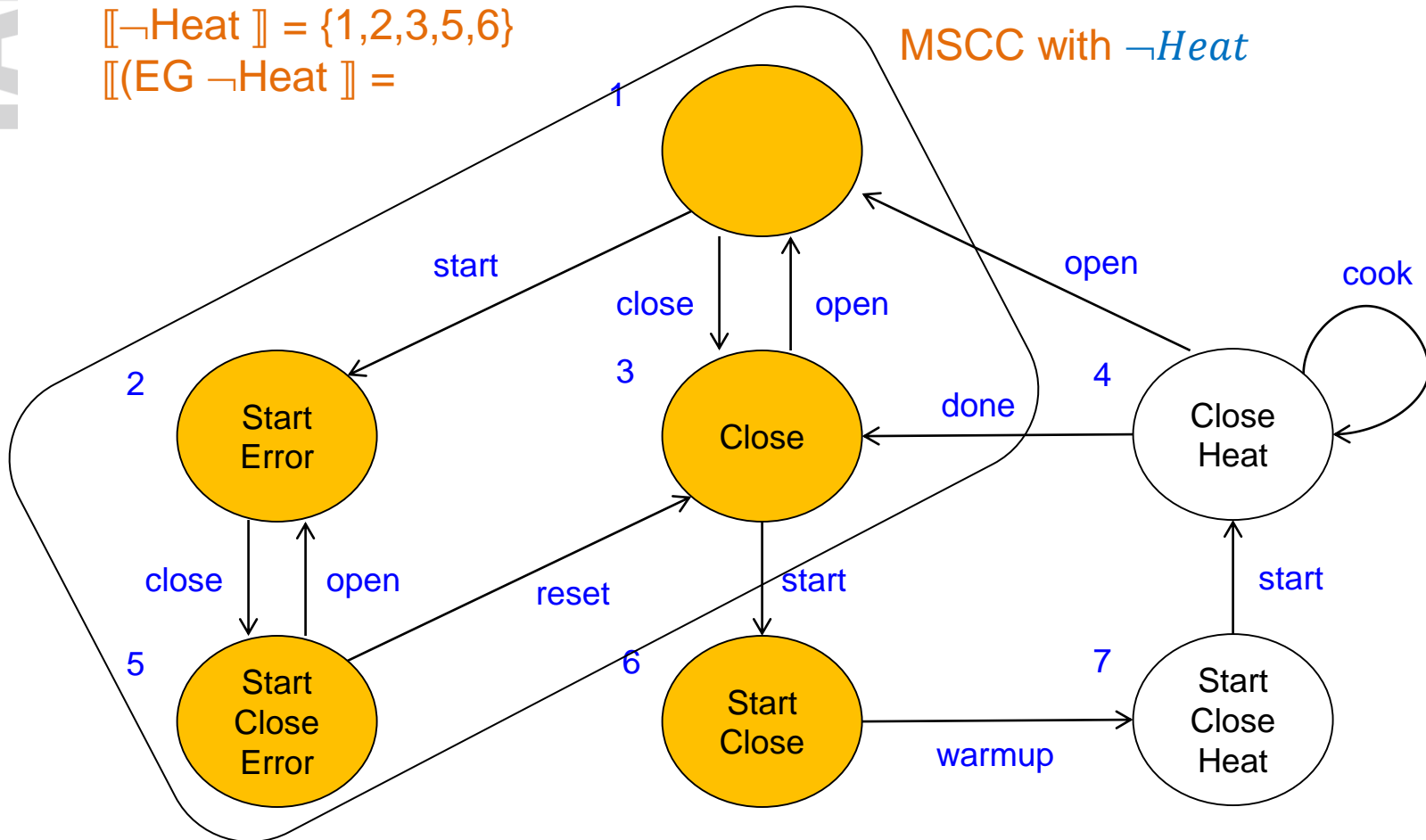
$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

$[[start]] = \{2,5,6,7\}$

$[[\neg Heat]] = \{1,2,3,5,6\}$

$[[EG \neg Heat]] =$

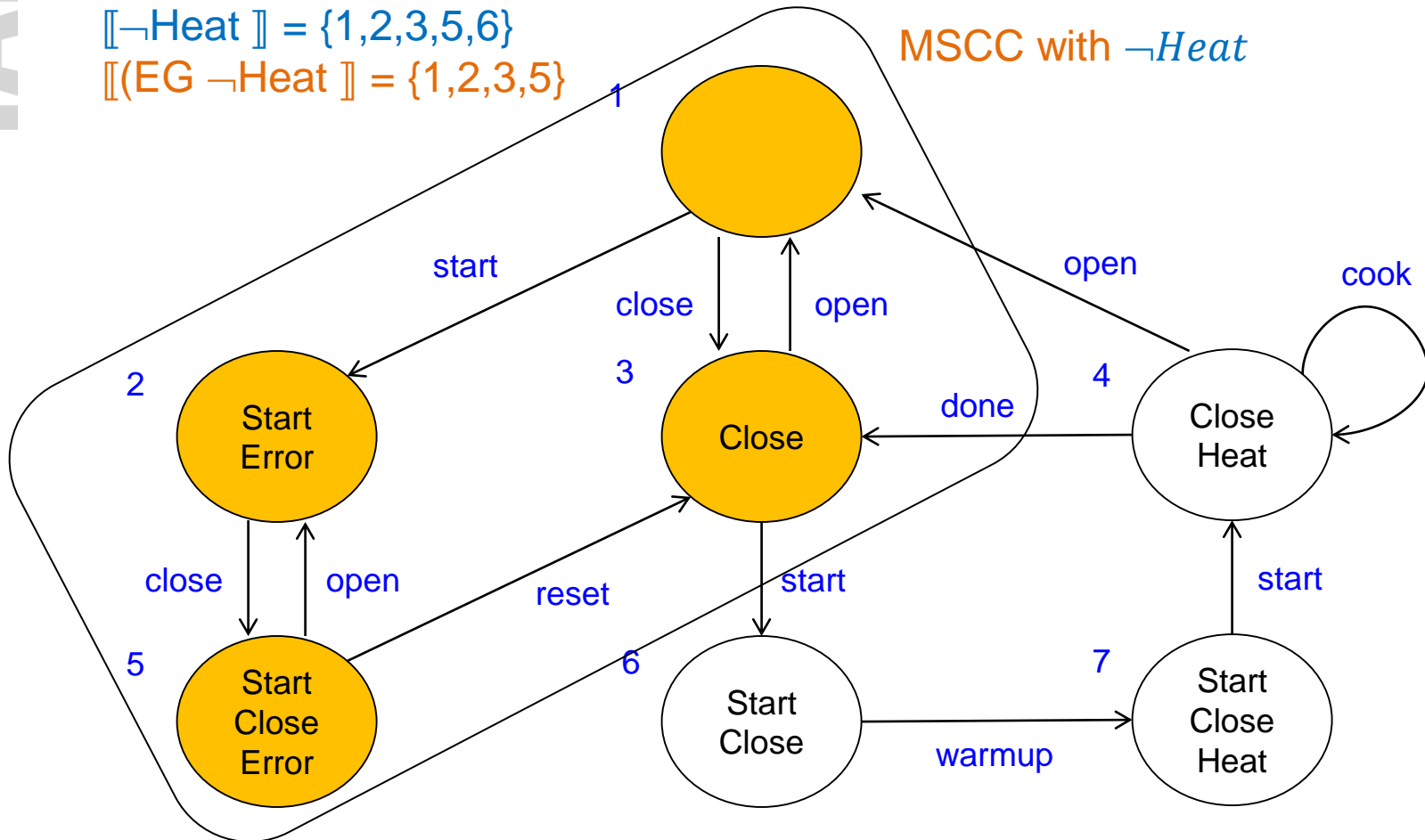
MSCC with  $\neg Heat$



$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

[[start]] = {2,5,6,7}  
 [[¬Heat]] = {1,2,3,5,6}  
 [[(EG ¬Heat)]] = {1,2,3,5}

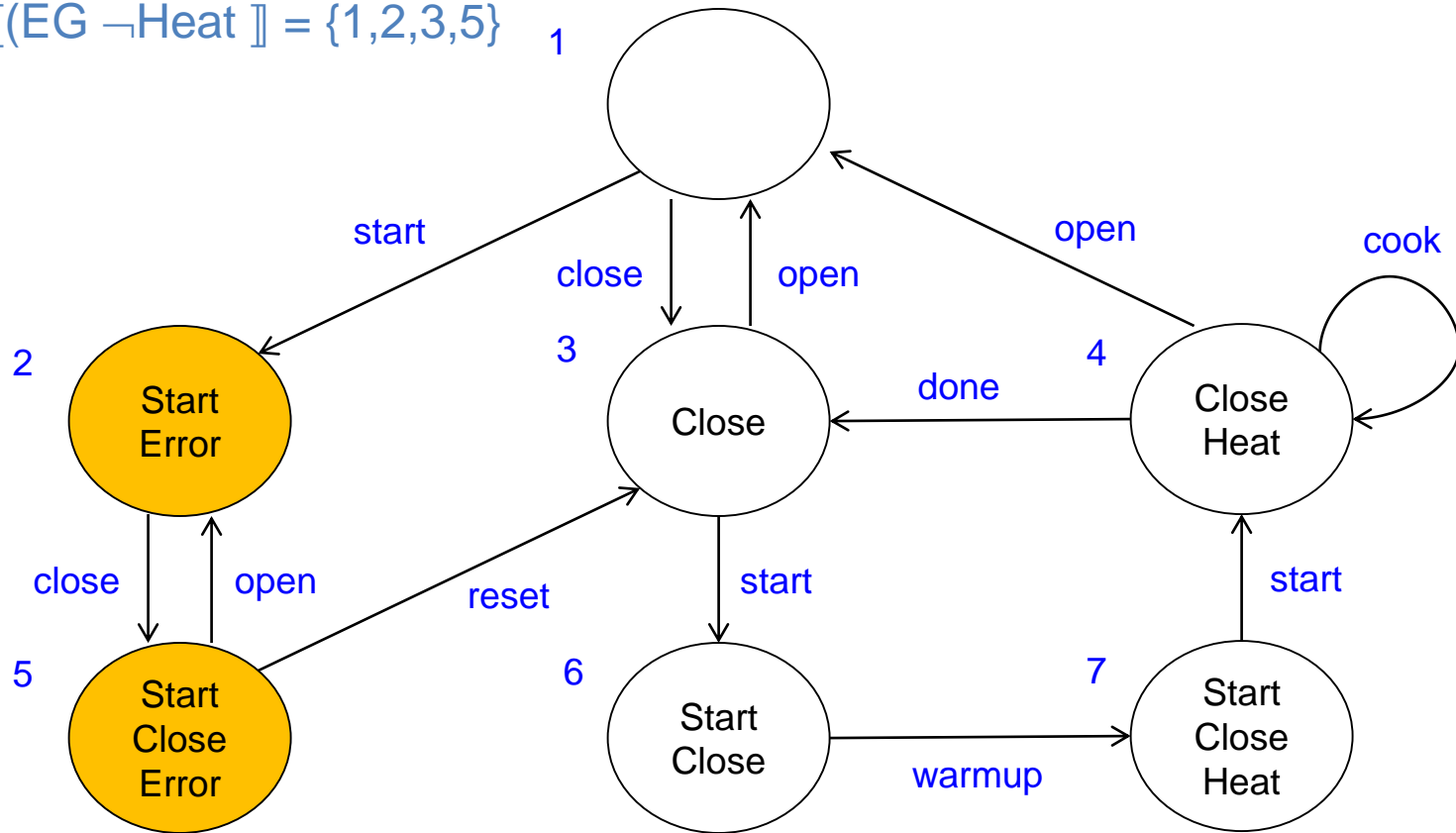
MSCC with ¬Heat



$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

$\llbracket start \rrbracket = \{2,5,6,7\}$   
 $\llbracket \neg Heat \rrbracket = \{1,2,3,5,6\}$   
 $\llbracket (EG \neg Heat) \rrbracket = \{1,2,3,5\}$

$\llbracket Start \wedge EG \neg Heat \rrbracket = \{2, 5\}$

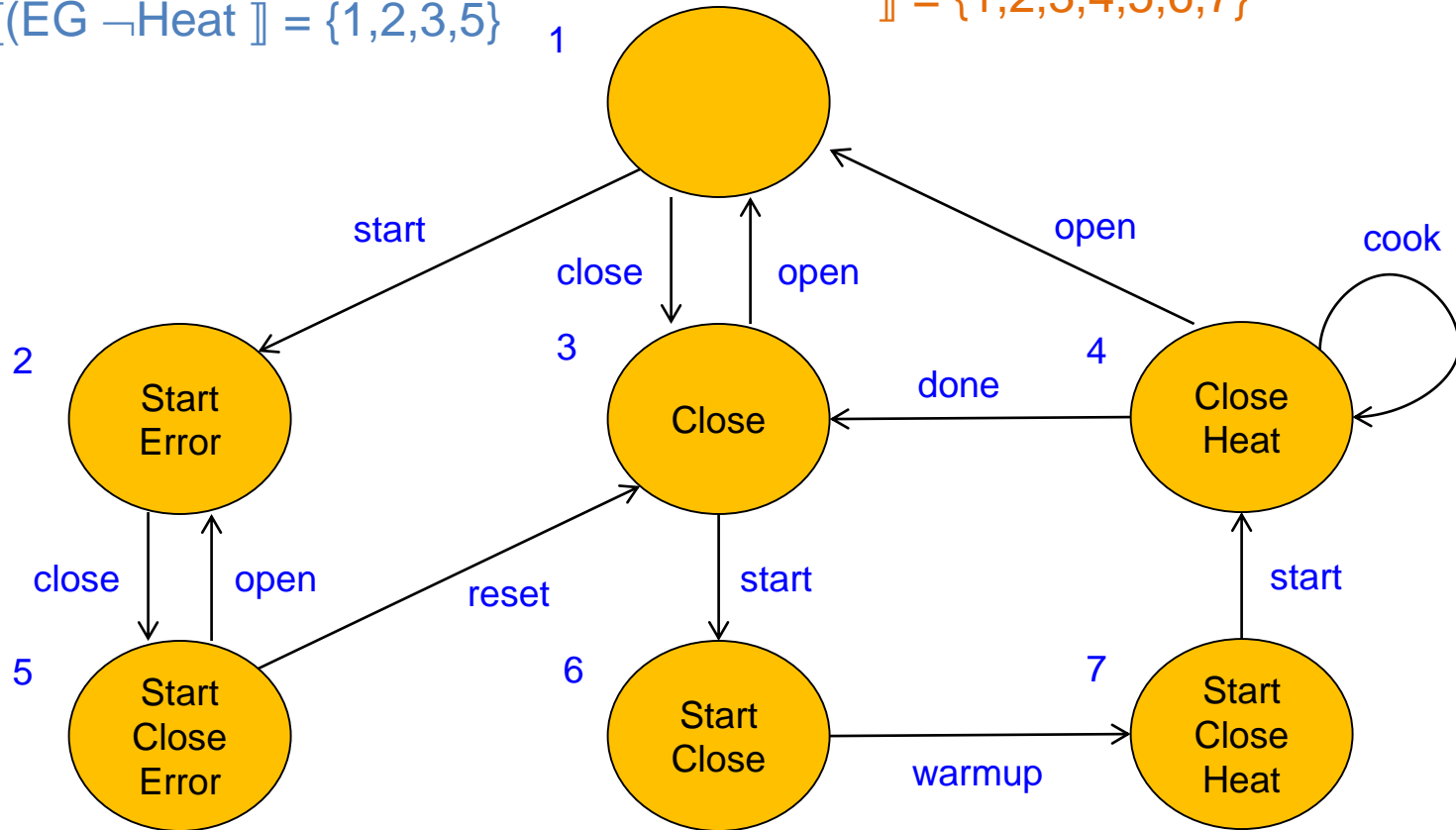




$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

$\llbracket start \rrbracket = \{2,5,6,7\}$   
 $\llbracket \neg Heat \rrbracket = \{1,2,3,5,6\}$   
 $\llbracket (EG \neg Heat) \rrbracket = \{1,2,3,5\}$

$\llbracket Start \wedge EG \neg Heat \rrbracket = \{2, 5\}$   
 $\llbracket E (true U (Start \wedge EG \neg Heat)) \rrbracket = \{1,2,3,4,5,6,7\}$



$$f := \neg E (true U (Start \wedge EG \neg Heat))$$

$\llbracket start \rrbracket = \{2,5,6,7\}$

$\llbracket \neg Heat \rrbracket = \{1,2,3,5,6\}$

$\llbracket (EG \neg Heat) \rrbracket = \{1,2,3,5\}$

$\llbracket Start \wedge EG \neg Heat \rrbracket = \{2, 5\}$

$\llbracket EU \rrbracket = \{1,2,3,4,5,6,7\}$

$\llbracket f \rrbracket = \emptyset$

