SoC Design Flow Tutorial

Digital System Integration and Programming

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IAIK – Graz University of Technology

- What we want?
  Run a bare-metal application on an FPGA

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  Run a bare-metal application on an FPGA
- What we have?
  A Zybo FPGA board, a hardware design, software
- How do we get there?
  1. Prepare FPGA board
  2. Build FPGA HW
  3. Build SW for HW
  4. Combine everything in a boot image
  5. Copy the boot image to the FPGA
  6. Run the application

Things could go wrong - and will. Don't expect anything to work out-of-the-box.

Install Vivado and Vitis (SDK)

- Xilinx Vivado: IDE for creating hardware designs
- Xilinx Vitis (SDK): SDK for embedded software
- Support for Xilinx FPGAs
- Installation: `https://www.xilinx.com/support/download.html`
  - Use version 2021.1
  - Use Linux Self Extracting Web Installer
  - Select Product to Install: first option (Vitis)
- Docker container: `https://github.com/Steinegger/vivado-docker/commit/f9f1390891ee7571ff5a367e6ba8665a37a89117`

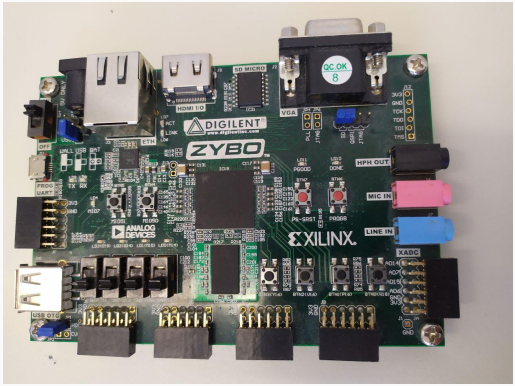
Possible Installation Problems

- Make sure to install `libtinfo5` and `libncurses5` beforehand!
- Useful log files: `~/.Xilinx/xinstall/xinstall_*.log`
- See also:
  `https://blog.lazy-evaluation.net/posts/linux/vivado-2018-3-buster.html`

Configuration of the Board

Zybo FPGA Board

- Zynq 7000 SoC
- Processor: 650Mhz dual-core Cortex-A9
- Memory: 512 MB
- Peripherals:
  - Ethernet, USB, MicroSD slot
  - Video: VGA and HDMI
  - Audio: headphone out, mircophone and line in
  - GPIO: 6 pushbuttons, 4 slide switches, 5 LEDs

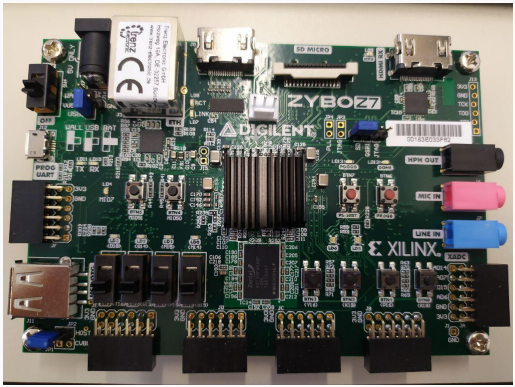


Configuration of Zybo FPGA Board

- Power source
  - JP7
  - Set to "USB"
- Boot source
  - JP5
  - Boot from SD card ("SD")
  - Other options: JTAG
  - Board falls back to JTAG mode when no SD card is found.
- Connect USB interface and optionally VGA/HDMI to test our base project.

Zybo Z7-20 FPGA Board

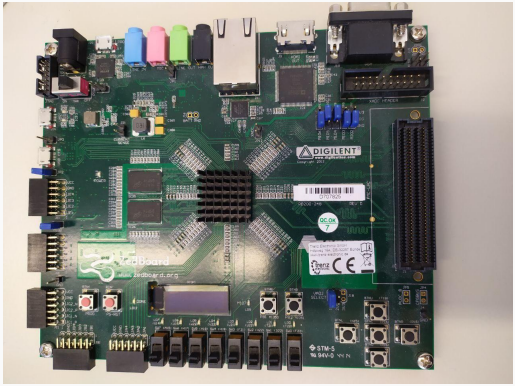
- Zynq 7020 SoC
- Processor: 650Mhz dual-core Cortex-A9
- Memory: 1 GB
- Peripherals:
  - Ethernet, USB, MicroSD slot
  - Video: VGA and HDMI
  - Audio: headphone out, mircophone and line in
  - GPIO: 6 pushbuttons, 4 slide switches, 5 LEDs, 2 RGB LEDs



- Power source
  - JP6
  - Set to "USB"
- Boot source
  - JP5
  - Boot from SD card ("SD")
- Connect USB interface and optionally VGA/HDMI to test our base project.

ZedBoard

- Zynq 7000 SoC
- same processor, memory and FPGA
- Peripherals: additional line out (Audio), 8 LEDs, ...



Configuration of ZedBoard

- Power source
  - 12V barrel jack, no USB available
- Boot source
  - JP10,JP9,JP8 set to 110
  - Boot from SD card ("SD")
- Connect USB interface and optionally VGA/HDMI to test our base project.

Building the FPGA Hardware

Start Vivado

- Export path to license server:
  `export XILINXD_LICENSE_FILE=2100@servitus.student.iaik.tugraz.at`
- Source Vivado environment settings:
  `source <VIVADO_ROOT>/Vivado/2021.1/settings64.sh`
- Install cable drivers:
  - `cd <VIVADO_ROOT>/Vivado/2021.1/data/xicom/cable_drivers/`
  - Execute install script.
  - Communication devices of board: `/dev/ttyUSB0`, `/dev/ttyUSB1`
  - Check if user has privileges to access devices (e.g. is member of dialout group)
- Start Vivado and initialize it with the basis project: `vivado`

Board files

```
ERROR: [Board 49-71] The board_part definition was not found
for digilentinc.com:zybo-z7-20:part0:1.0. The project's board_part
property was not set, but the project's part property was set to
xc7z020clg400-1. Valid board_part values can be retrieved with the
'get_board_parts' Tcl command. Check if board.repoPaths parameter
is set and the board_part is installed from the tcl app store.
```

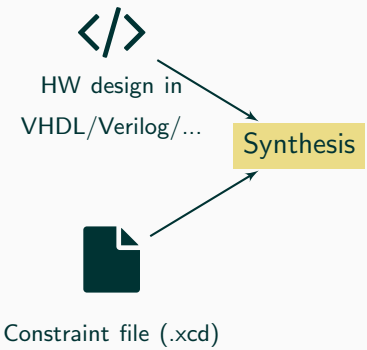
- Clone `https://github.com/Digilent/vivado-boards`
- Copy `vivado-boards/new/board_files` including all subdirectories to `<VIVADO_ROOT>/Vivado/2021.1/data/boards/`
- Further details: `https://digilent.com/reference/programmable-logic/guides/installing-vivado-and-sdk?redirect=1#installing_digilent_board_files`

Building the FPGA Hardware

HW design in
VHDL/Verilog/...

Constraint file (.xcd)

Building the FPGA Hardware



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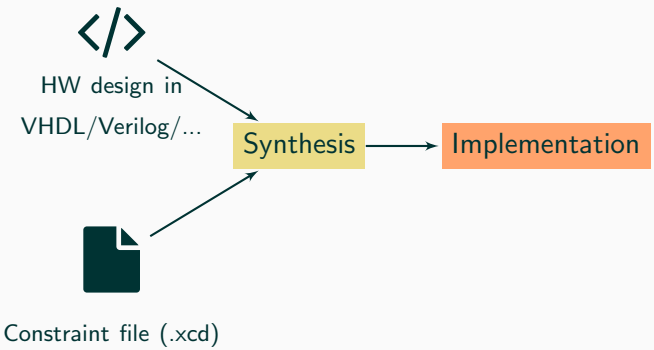

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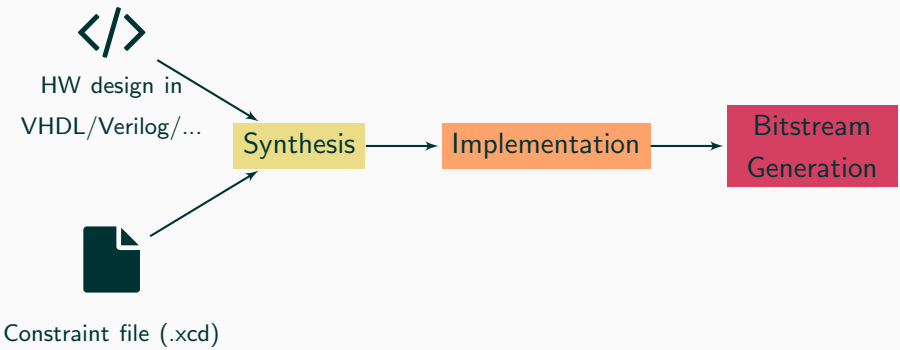

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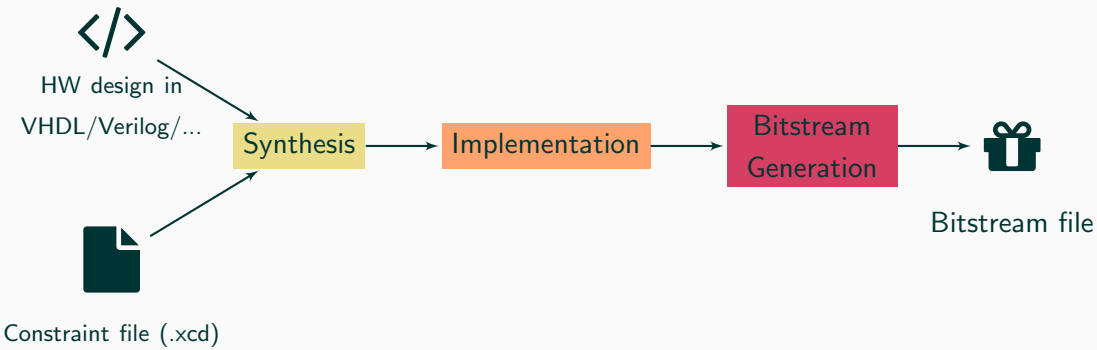

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Synthesis

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- Each gate is replaced by an architecture-specific block according to cell library:
  - Example: replace AND gate #1537 by macro `LUT4`, a 4-input Look-Up Table
  - Specification: `https://www.xilinx.com/support/documentation/sw_manuals/xilinx2012_2/ug953-vivado-7series-libraries.pdf`

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- Output: netlist tailored towards the FPGA on our ZYBO Board

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- Floor planning, placement and routing, optimizations for specific architecture

Implementation

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- Example: Netlist element *AND #1537* which requires `LUT4` is assigned *LUT4 #20A5* on the FPGA

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- Output: map of netlist elements to FPGA blocks $\rightarrow$ FPGA configuration

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Bitstream Generation

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- Programming FPGA = write bitstream file into FPGA memory
- On boot: FPGA loads configuration from memory and programs all LUTs

In Vivado...

1. Download suitable base project:

   `https://extgit.iaik.tugraz.at/sip/zybo_base_design`

   `https://extgit.iaik.tugraz.at/sip/zybo_z7_base_design`

   `https://extgit.iaik.tugraz.at/sip/zedboard_base_design`

2. Generate Project: `cd <PROJECT_ROOT>/HW && vivado -source project.tcl`
3. Synthesis + Implementation + Bitstream Generation: Flow - Generate Bitstream

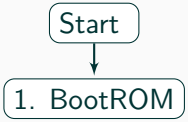
   Note: takes around 15 minutes the first time
4. Export hardware to SDK project: File - Export - Export Hardware
   - Include Bitstream

Building the ARM Software

Start Vitis

- Simplest option: In Vivado, Tools - Launch Vitis IDE
- Keep default options for Exported Location and Workspace
- Otherwise, start Vitis similar to Vivado via console

Figure 1: Zynq-7000 Boot Flow [1]



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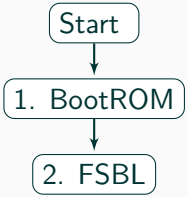

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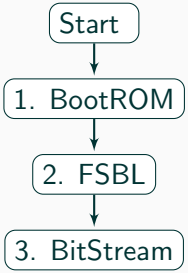

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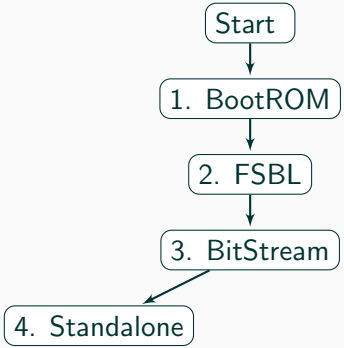

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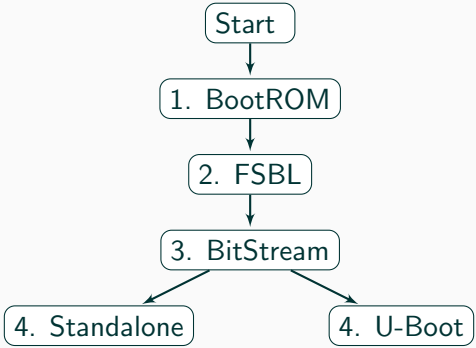

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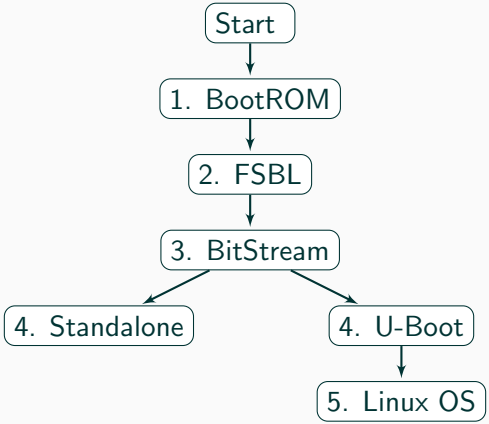

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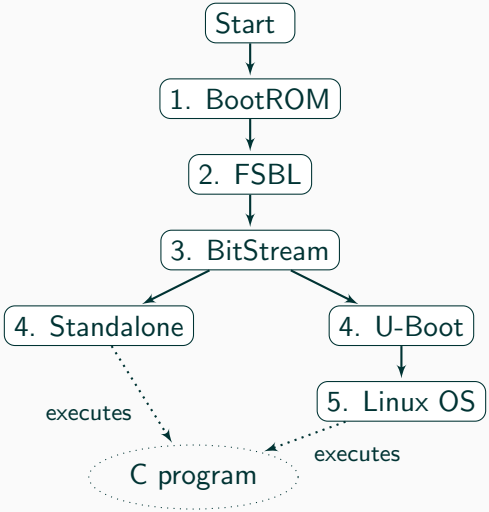
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2. FSBL
3. BitStream
4. Standalone
4. U-Boot
5. Linux OS
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executes
C program

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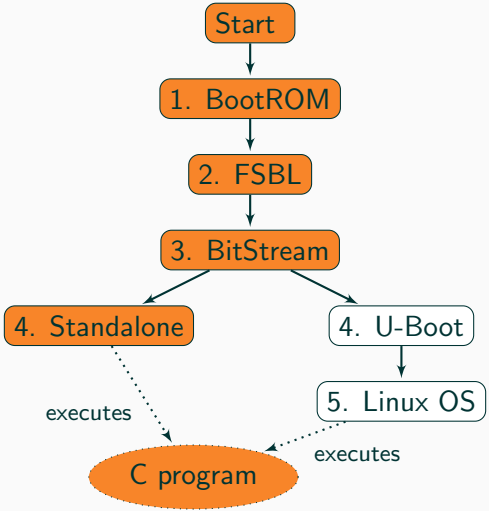
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1. File - New - Application Project
   - Use default location
   - Platform: Create new platform from hardware...
   - Select Hardware Specification/XSA File from `<PROJECT_ROOT>/HW/zybo_bsd/system_wrapper.xsa`
   - Generate boot components
2. Copy the base demo sources into the project's `src` directory
3. Build project

Running the design

Creating a Boot Image (in SDK)

- Zynq SoCs combine FSBL, Bitstream and SW into one boot image (BOOT.bin)
- Select SW project, Create Boot Image
- Select correct paths for FSBL, Bitstream and SW (in this order!)
  - Should be correct by default
- Alternatively: run bootgen directly

```
bootgen -image <IMAGE.BIF> -arch zynq -o <OUTPUT_FILE.BIN>
```

- Copy the boot image to SD card
  - First partition: FAT32, around 50 MB, used for boot files (BOOT.bin)
  - Second partition: ext4 or other, used as root file system and data storage
  - Use standard tools to create them (gparted, fdisk+mkfs ,..)
- Insert the SD card into the board
- Power up the board via SW4
- The red power LED (LD11) and the green FPGA programmed LED (LD10) should be on.
- Test image should be displayed via VGA/HDMI.

- Use the virtual serial interface
- Typically: `/dev/ttyUSB1`
- Configuration: 115200 baud, 8 data bits, 1 stop bit, no parity
- `screen /dev/ttyUSB1 115200`

Running the application via JTAG

- Alternative to SD card
- Either correct jumper setting (JP5 to JTAG) or remove SD card
- Power up the board
- Program FPGA: In Vitis (SDK), Xilinx - Program FPGA
- Run binary: Run - Run As - 1 Launch on Hardware (System Debugger)
- Debug binary: Run - Debug As - 1 Launch on Hardware (System Debugger)
- Alternatively, via command line in xsdb console:

```
cd <IMAGE\_ROOT>/base\_demo && xsdb run_base_demo.tcl
```

Links and Resources

- Xilinx Installation Resources:
  - https://www.xilinx.com/support/download.html
  - https://forums.xilinx.com/t5/Installation-and-Licensing/Installation-of-Vivado-2020-1-under-Centos-7-8-fails/td-p/1115482
  - https://www.xilinx.com/html_docs/xilinx2020_1/vitis_doc/aqm1532064088764.html
- ZYBO FPGA Board Reference Manual

  https://reference.digilentinc.com/_media/zybo:zybo_rm.pdf
- ZYBO-Z7 Reference Manual

  https://reference.digilentinc.com/_media/reference/programmable-logic/zybo-z7/zybo-z7_rm.pdf
- ZedBoard Reference Manual

  https://reference.digilentinc.com/_media/zedboard:zedboard_ug.pdf

References

[1] X. Inc., UltraFast Embedded Design Methodology Guide,, 2018. [Online]. Available: https://www.xilinx.com/support/documentation/sw_manuals/ug1046-ultrafast-design-methodology-guide.pdf.